

COMPENSATING FOR THERMAL AND GRAVITATIONAL EFFECTS IN STRUCTURES AND ASSEMBLIES

David Ross-Pinnock, Glen Mullineux
University of Bath, UK

LUMINAR Workshop - NPL - 18-19 May 2016

This work was funded by the EMRP Project IND53. The EMRP is funded by the EMRP participating countries within EURAMET and the European Union. The authors gratefully acknowledge this support and the help and encouragement of all those involved.

Thermal expansion
one of the largest
contributors to
measurement
uncertainty

Costly or impractical to control
temperature closely at large volume scale

Standard metrology
temperature is 20°C

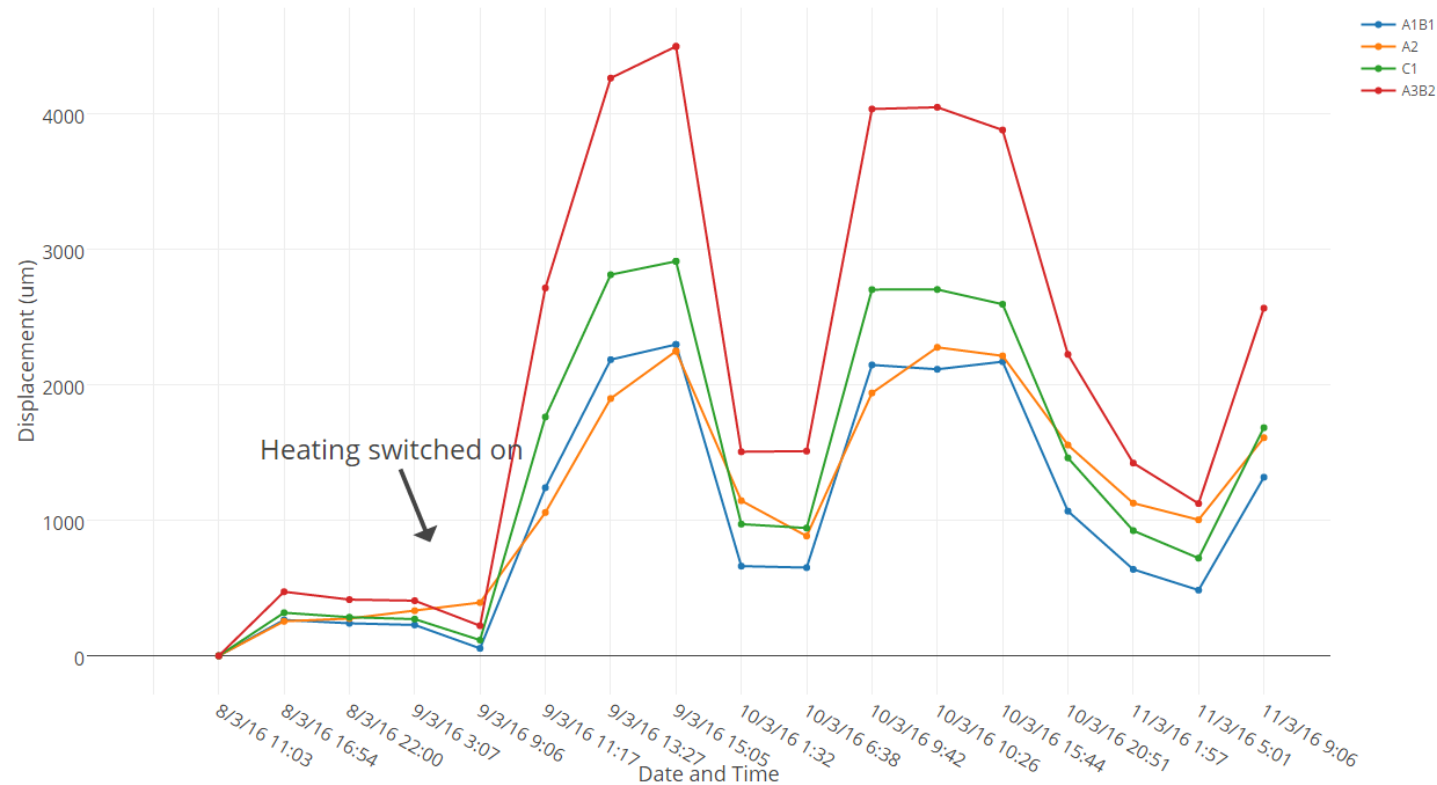
Need to create a
method to
compensate for
thermal effects

Uniform and linear
scaling can produce
unrealistic results in
anisothermal
environments

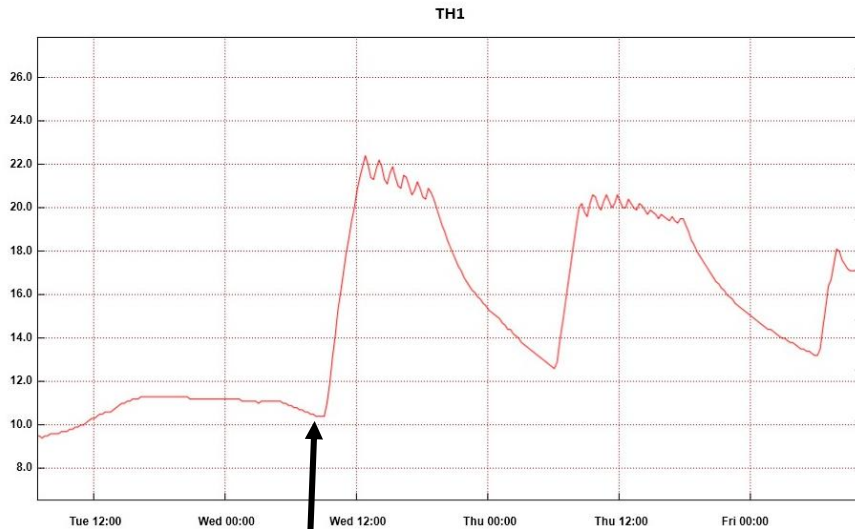


- Wing bending test rig at Airbus (UK)
- Dimensional measurements taken on structure with laser tracker
- Temperature monitored on the structure

Graph of total displacement at 4 measured points over time



- Laser tracker measurement
- 4 measured points on structure
- Additional 7 reflectors measured
- Repeated at regular time intervals throughout the day

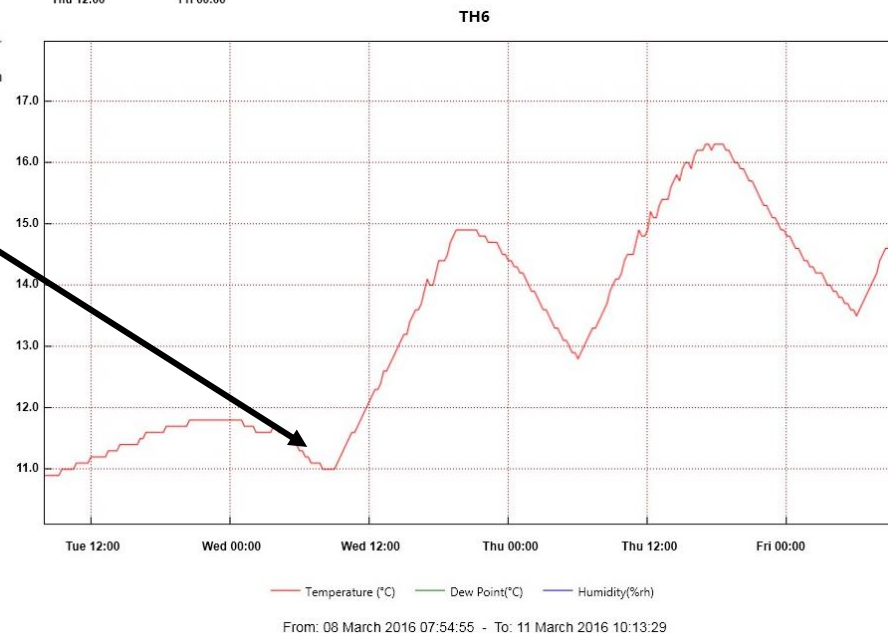


Temperature
at the top

- Temperature monitored around volume
- 10 WiFi ambient temperature and humidity data loggers
- 10 wireless data loggers

Heating
switched on

Temperature
at bottom



Would like to be able to know:

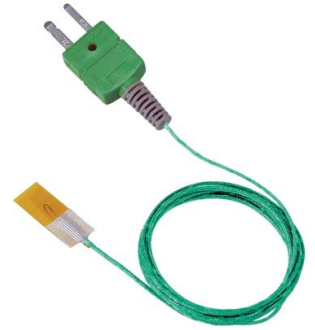
- “true” geometry exactly
- if subsequent operations will work
- what remedial action is required



Temperature:

- component
- environment

- thermocouples
- thermal imaging





National Instruments 8-Slot Data Acquisition Chassis



National Instruments 16-channel Thermocouple Module



13 Type T and 18 Type K Thermocouple Sensors ($\pm 0.5^{\circ}\text{C}$)



9 Omega Wireless Temperature Transmitters (18 thermocouple channels)



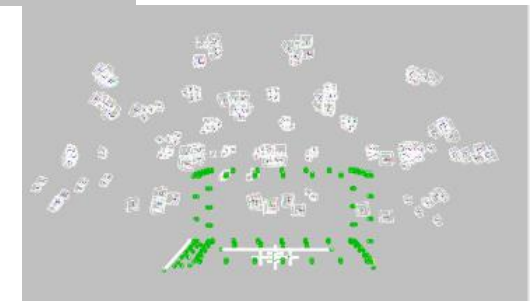
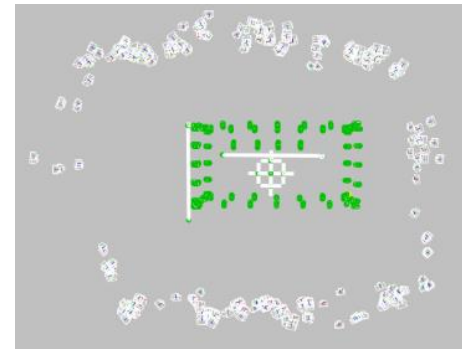
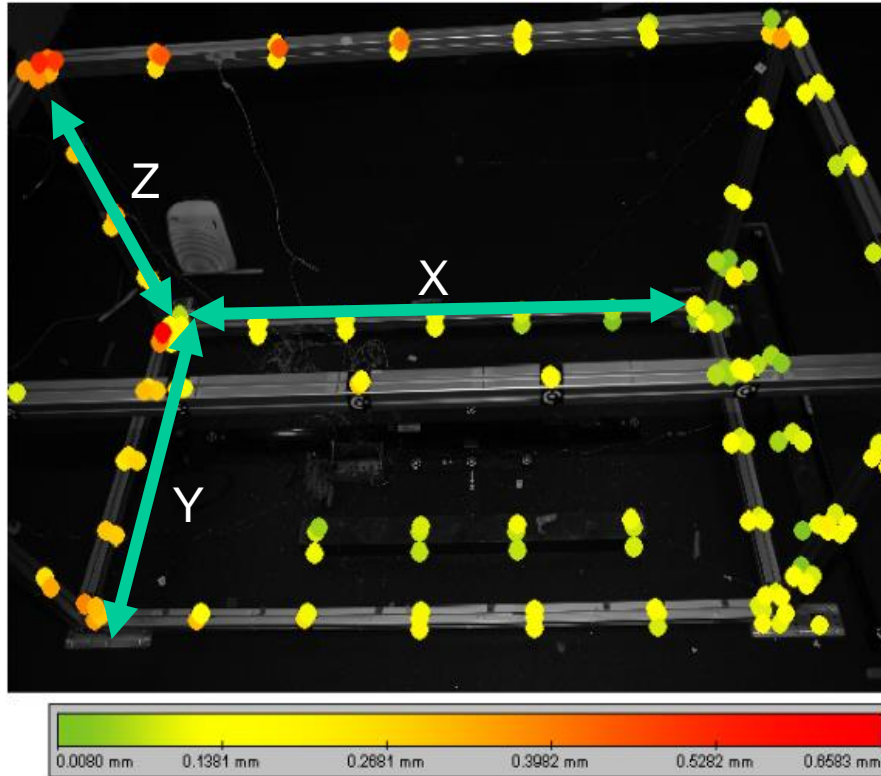
- Laser tracker
- Invasive temperature sensors



Position:

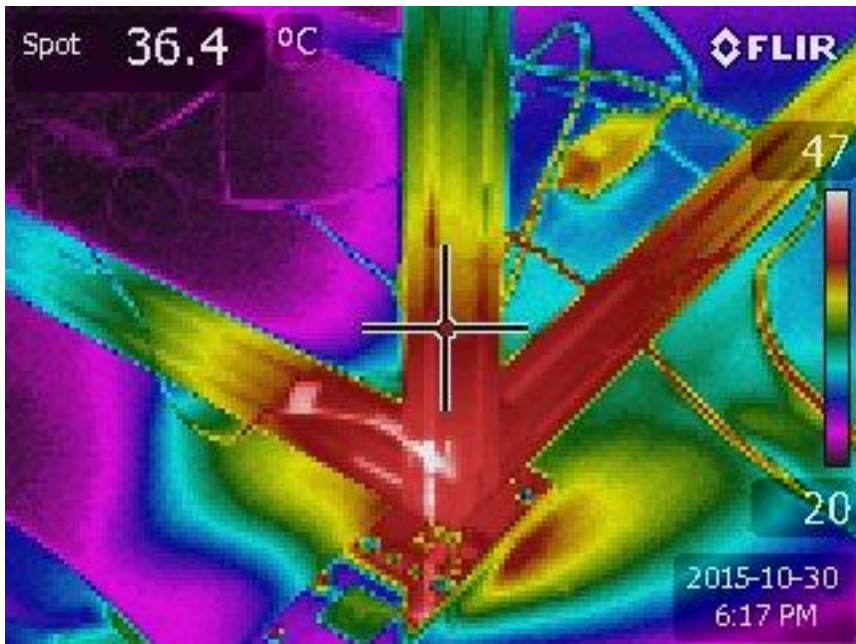
- points on component
- photogrammetry
- laser tracking





- Example photograph captured during photogrammetry overlaid with target total deformation
- Measurement uncertainty of points: 13-40 μm

- used qualitatively to plan sensor positions
- also used quantitatively to validate finite element thermal analysis

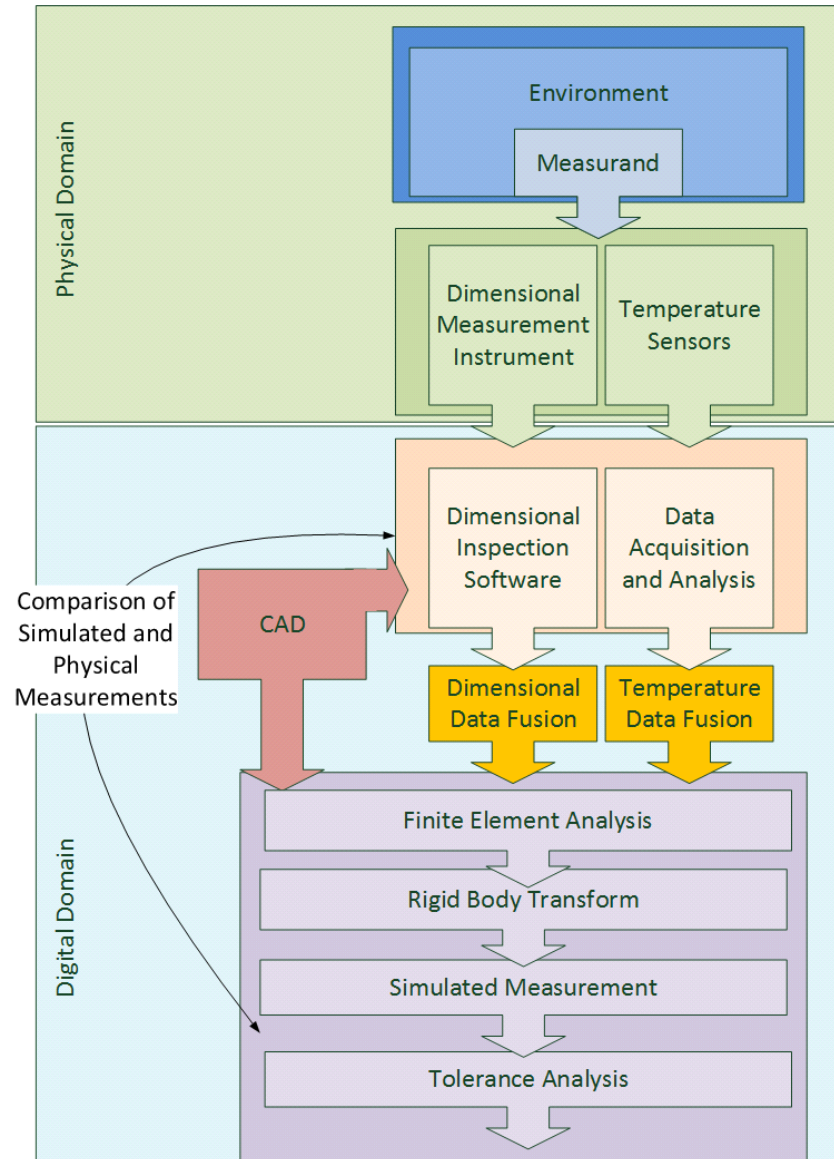


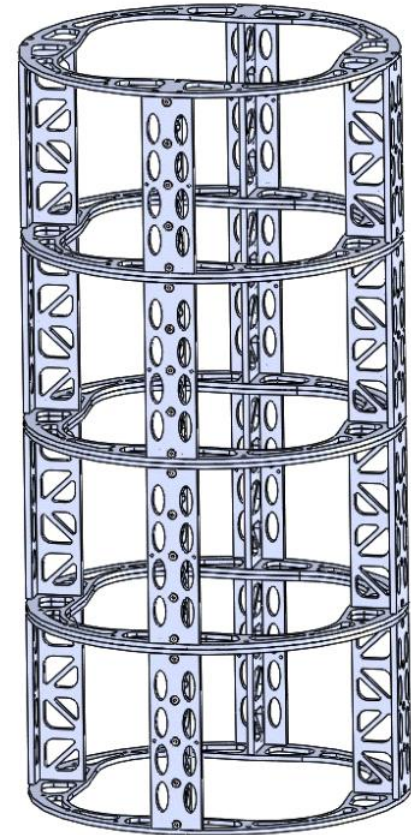
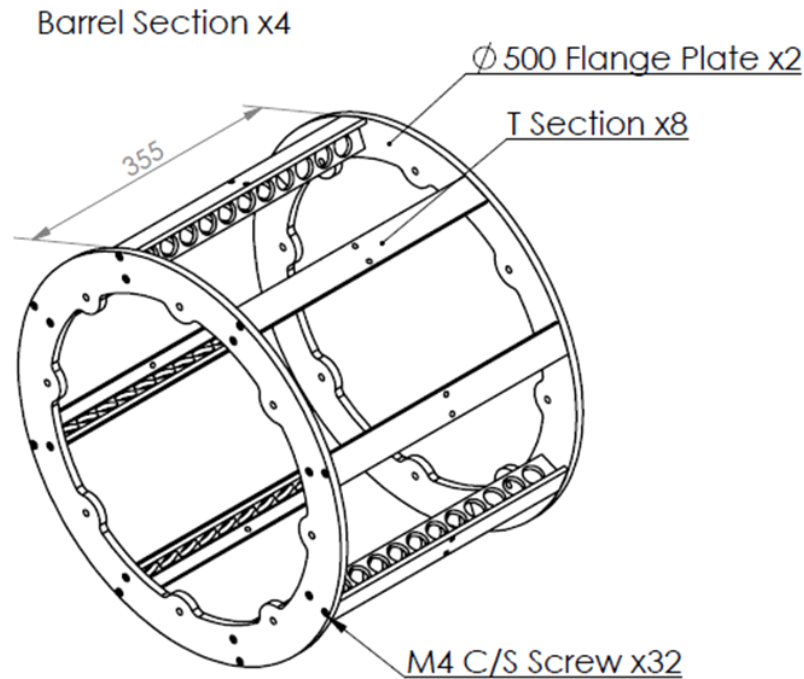
Heater setting 2, position 1



Heater setting 1, position 2

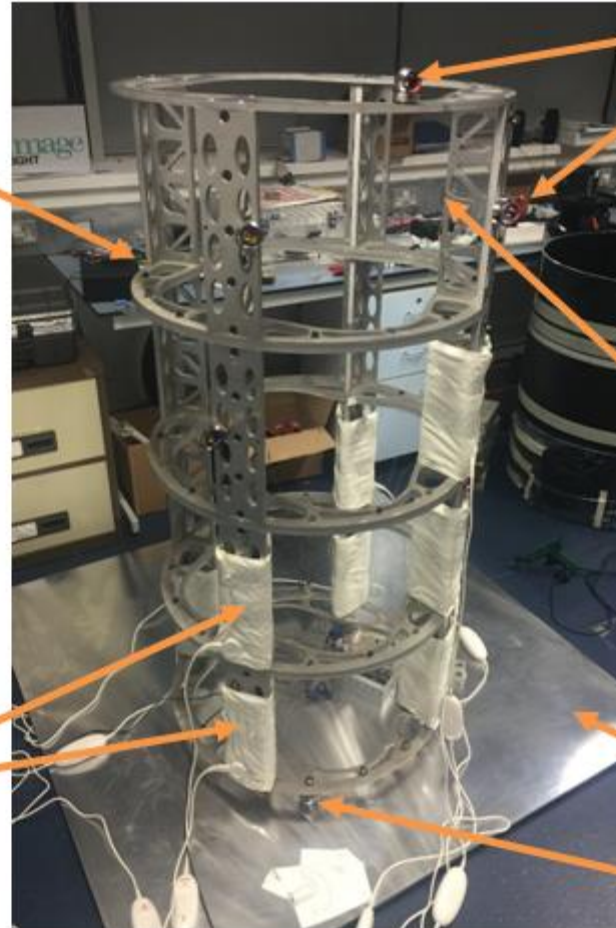
Hybrid approach





Experimental set-up

Structure assembled
using 4 barrel sections



SMR targets to
measure surface and
hole positions

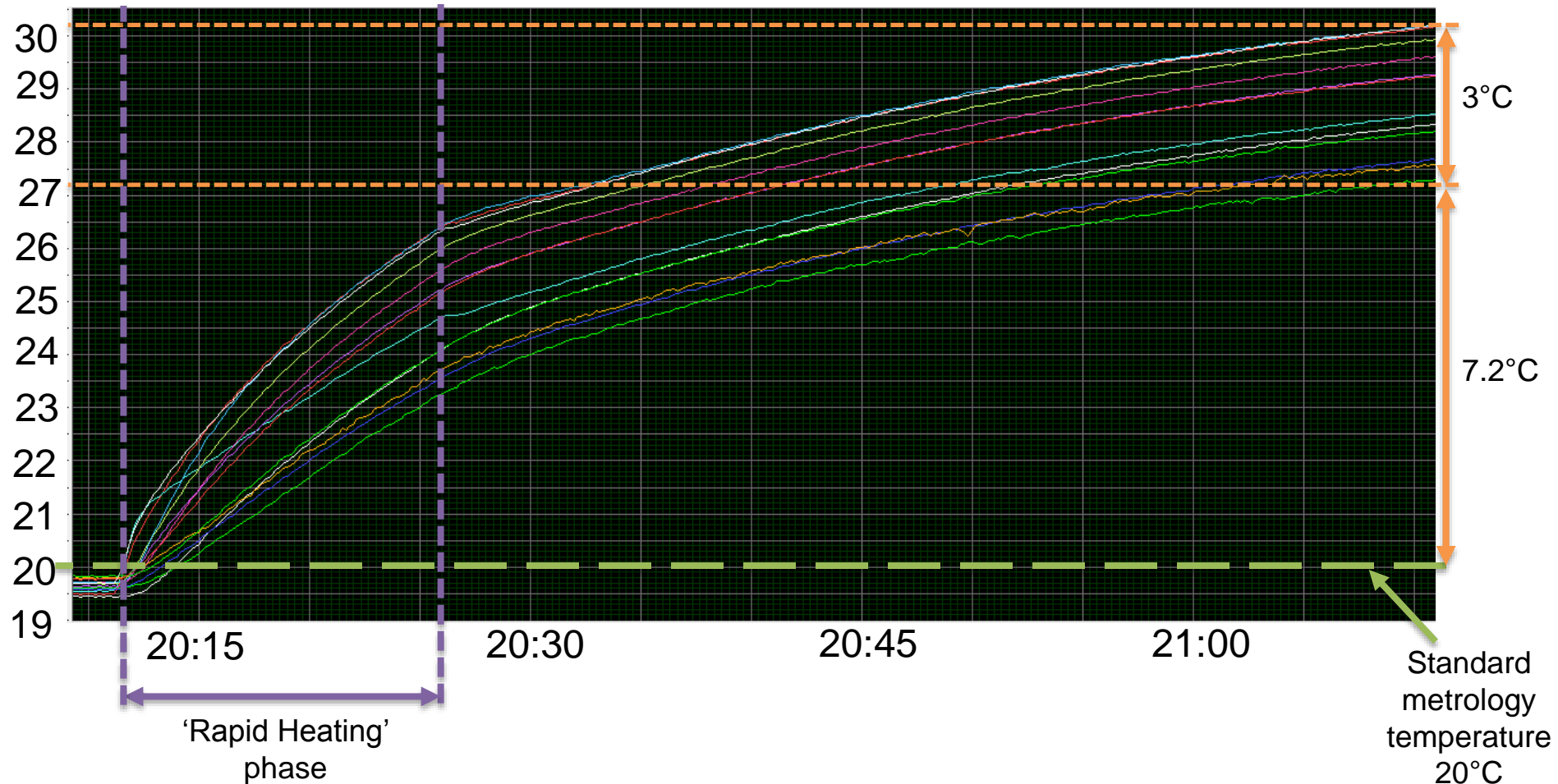
13 thermocouples to
measure surface
temperature

Heating pads X8

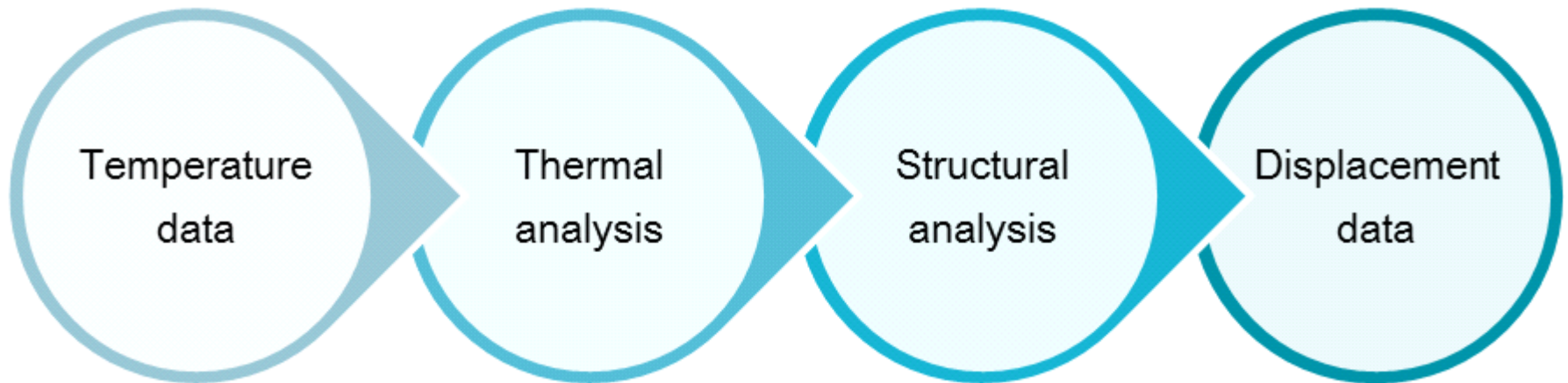
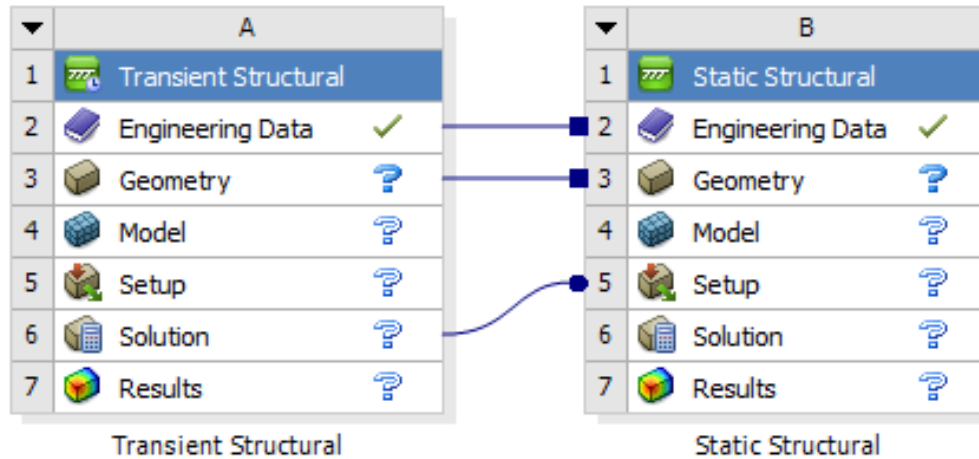
Aluminium tooling
plate

3-2-1 constraint using
3 tooling balls

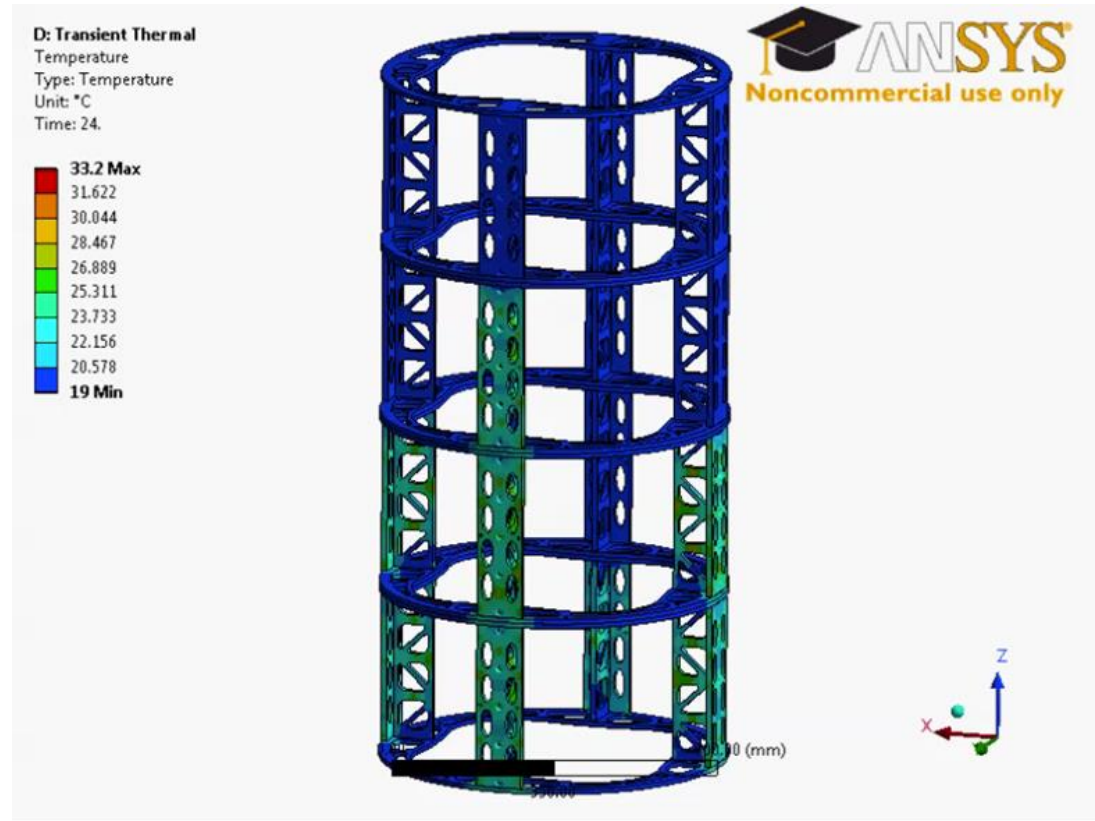
Heating profile



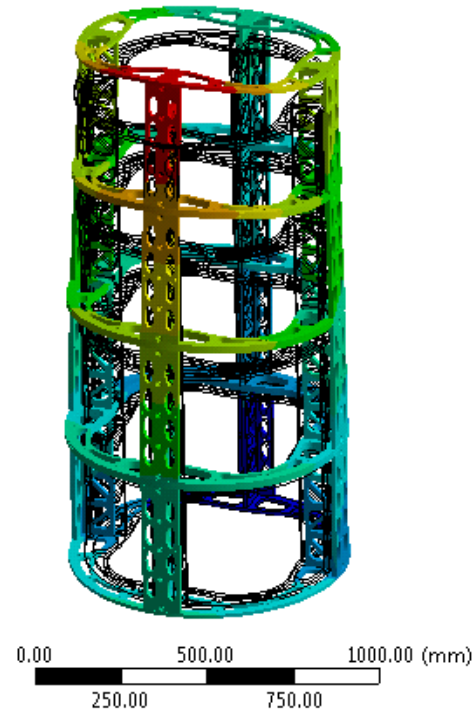
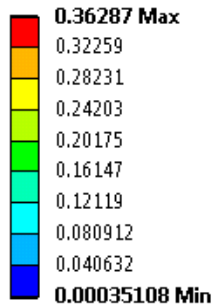
Steps of finite element analysis



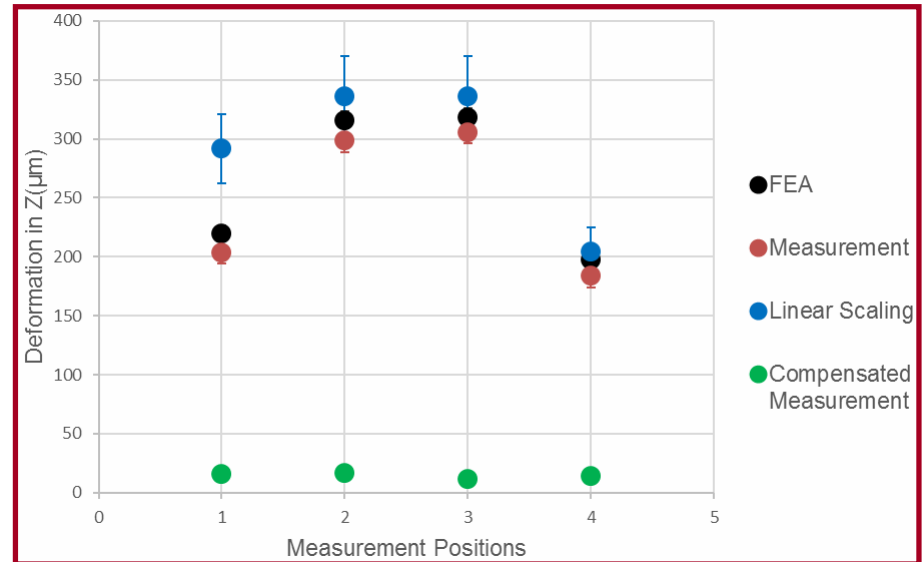
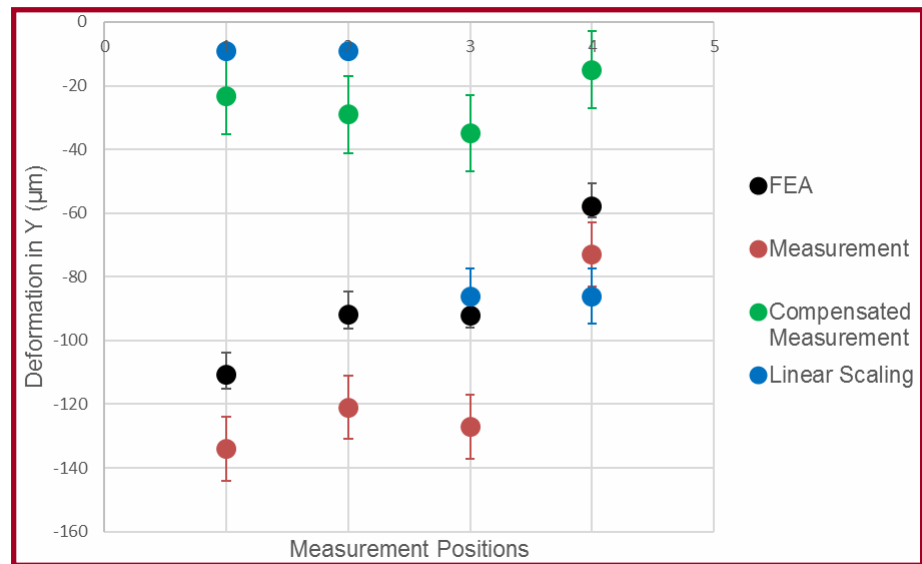
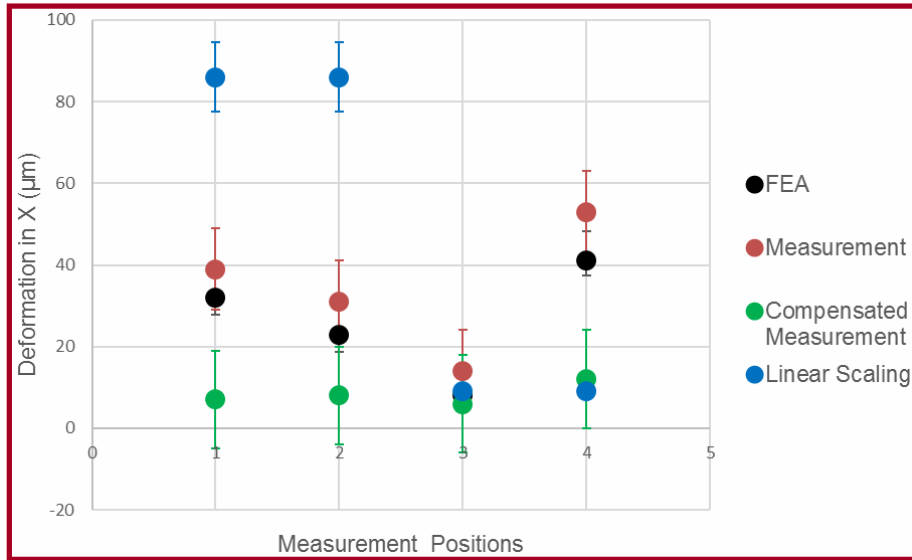
- Transient preferable as temperature does not stabilise
- Solution calculates temperature distribution at all nodes of model over time
- More time steps → more accurate prediction
- Temperature applied to nodes nearest the sensor position

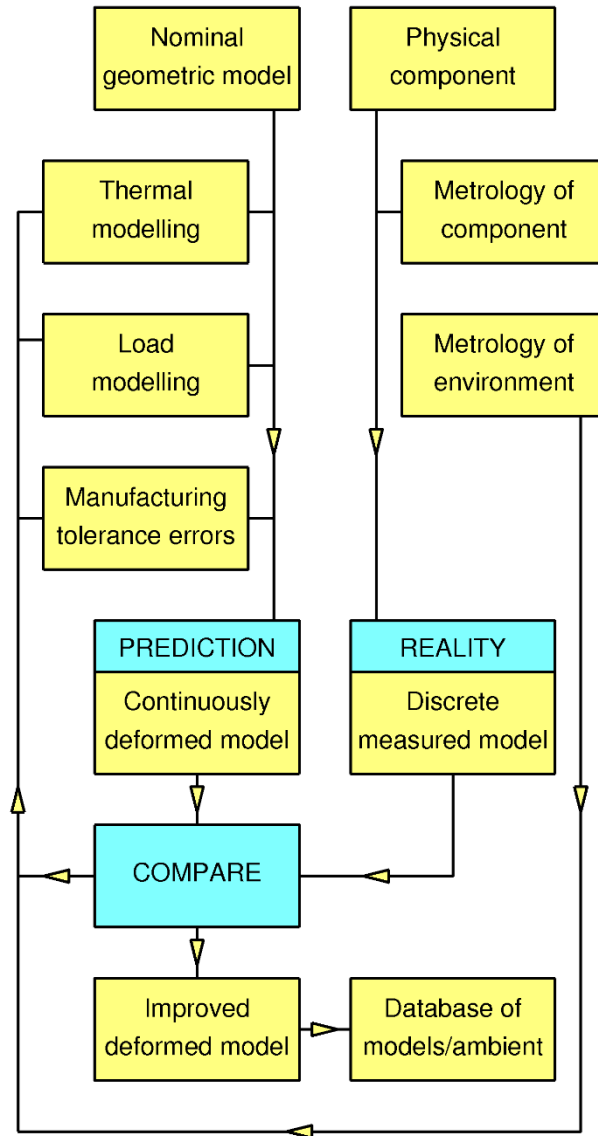


Total Deformation
Type: Total Deformation
Unit: mm
Time: 1

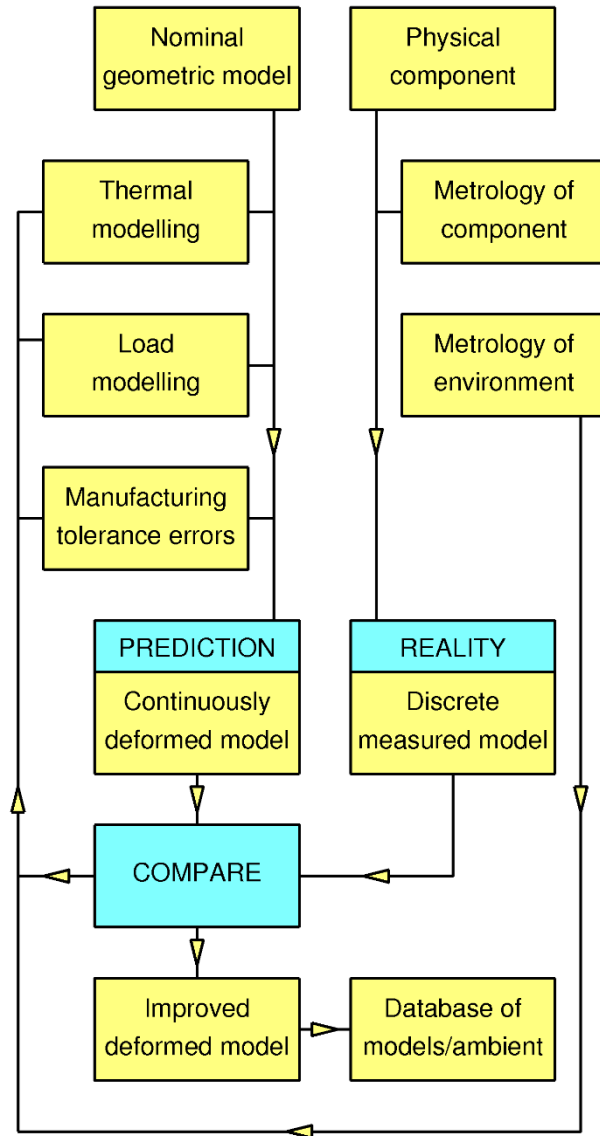


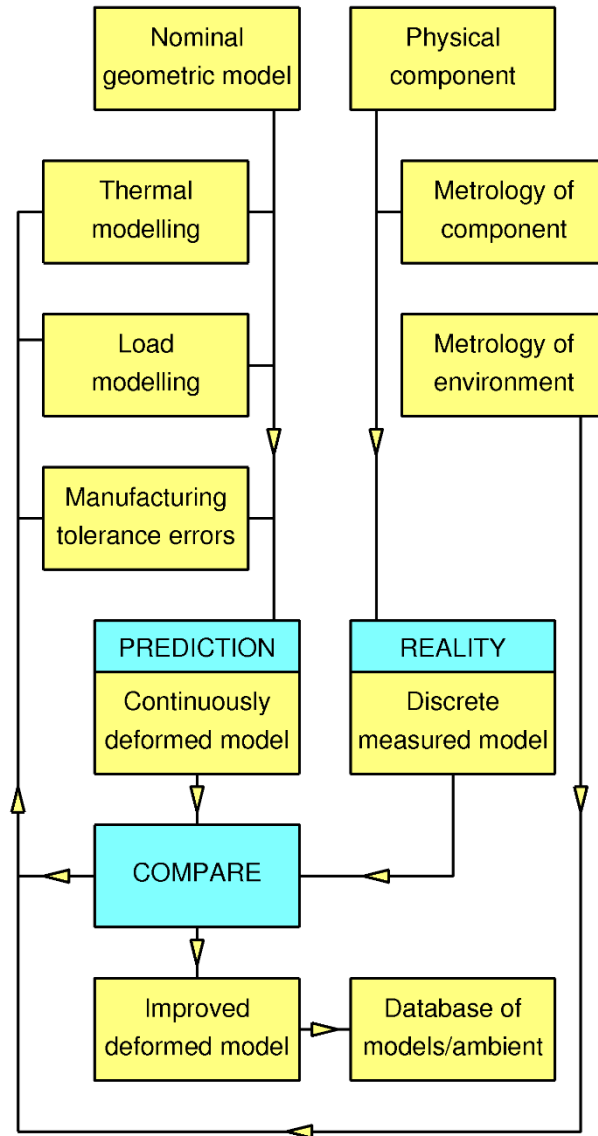
- Normal gravity applied
- Assumes structure is perfectly level
- Solution calculates displacement in X, Y and Z axes at all nodes of model
- Solution also calculates total displacement
- Support: movement in Z constrained, X and Y free





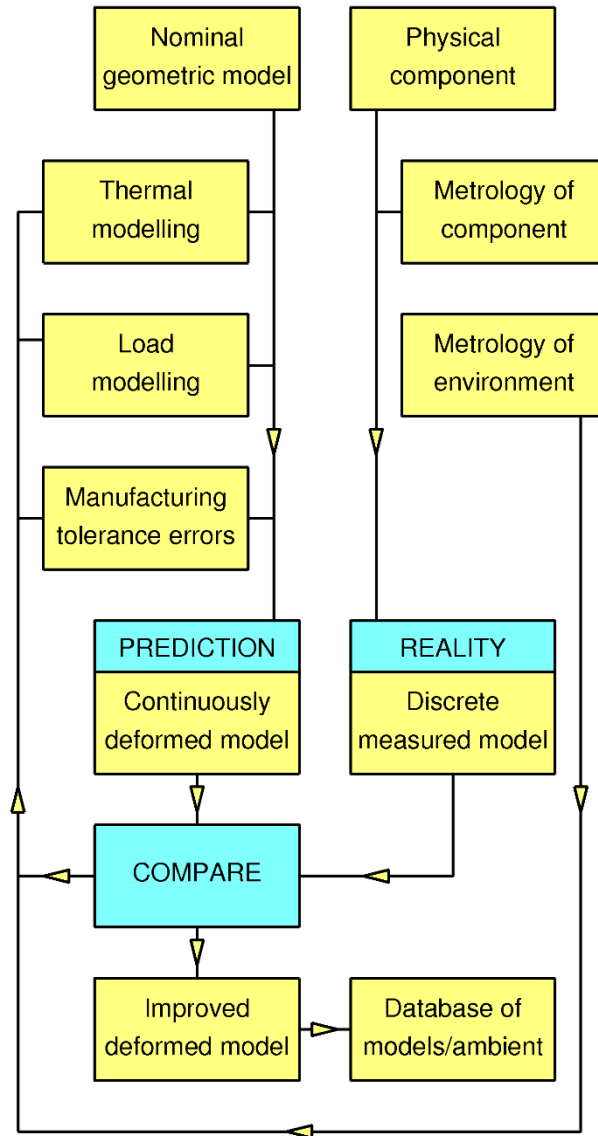
Two “models”: geometric, physical





Two “models”: geometric, physical

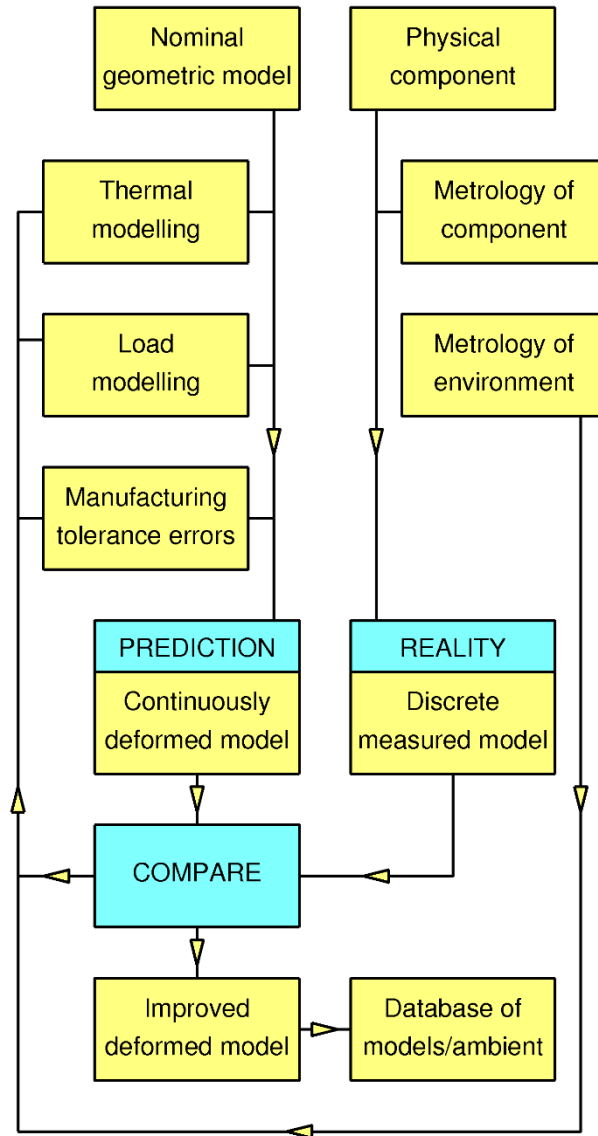
Physical: measure



Two “models”: geometric, physical

Physical: measure

Geometric: FE analysis

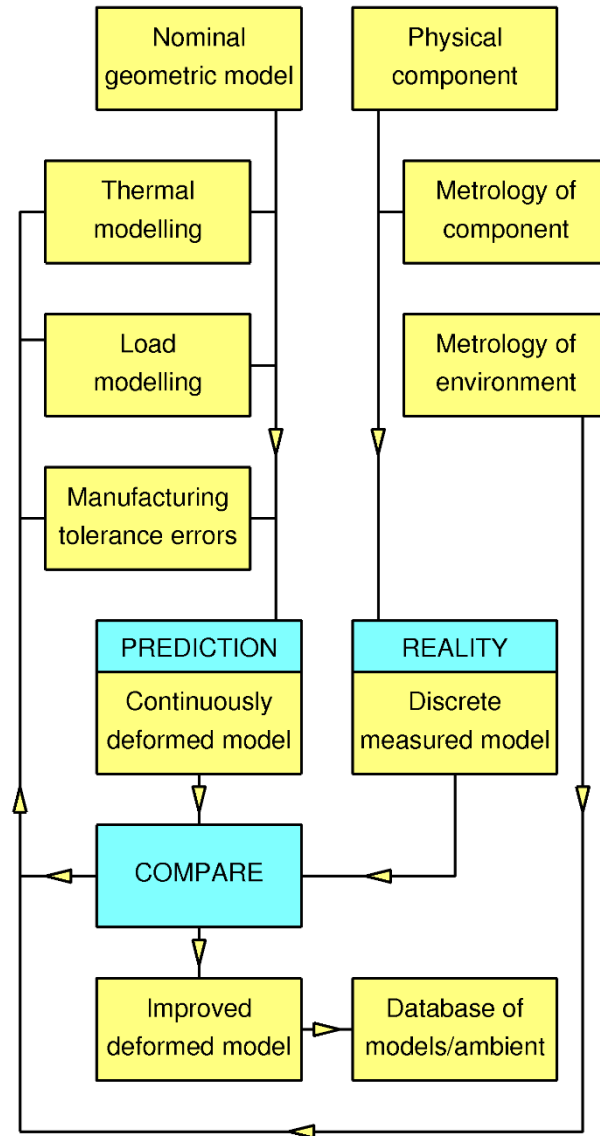


Two “models”: geometric, physical

Physical: measure

Geometric: FE analysis

Prediction and reality



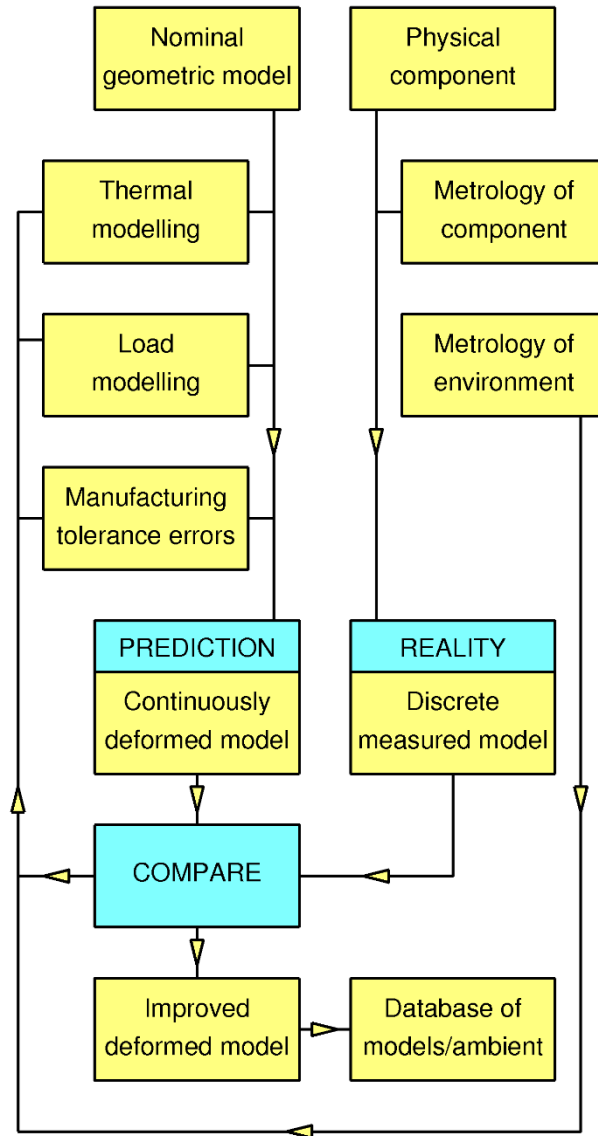
Two “models”: geometric, physical

Physical: measure

Geometric: FE analysis

Prediction and reality

Comparison



Two “models”: geometric, physical

Physical: measure

Geometric: FE analysis

Prediction and reality

Comparison

Improved model

Geometric/FE:

- point-based (nodes)
- large number of nodes

Measured:

- point-based
- small number of nodes

Geometric/FE:

- point-based (no
- large number of

Subject to errors due to assumptions in modelling and numerical effects in solving

Measured:

- point-based
- small number of nodes

Geometric/FE:

- point-based (no
- large number of

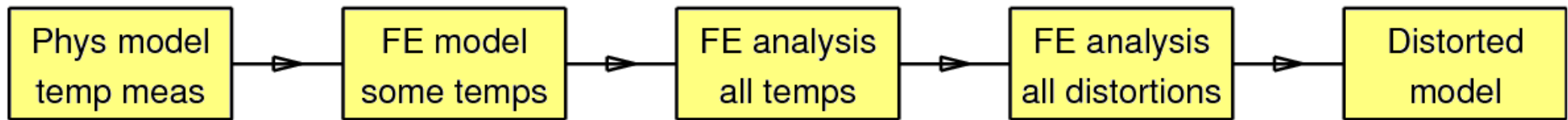
Subject to errors due to assumptions in modelling and numerical effects in solving

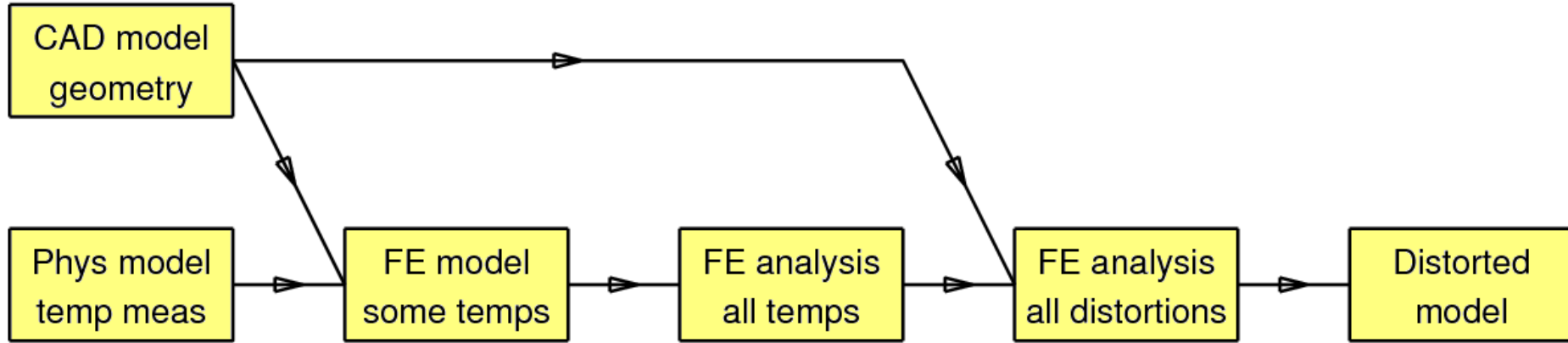
Measured:

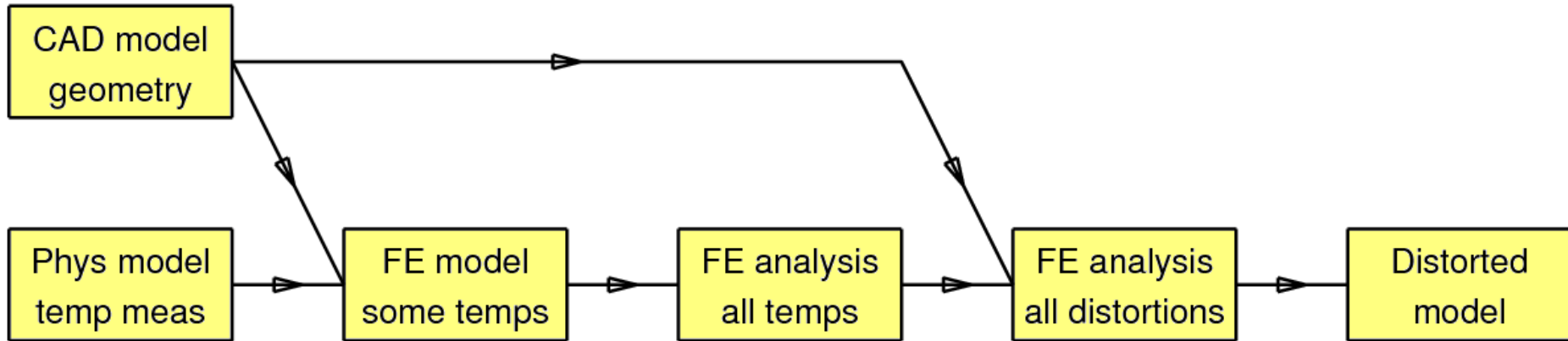
- point-based
- small number of

Best information about actual component (but subject to measuring errors)

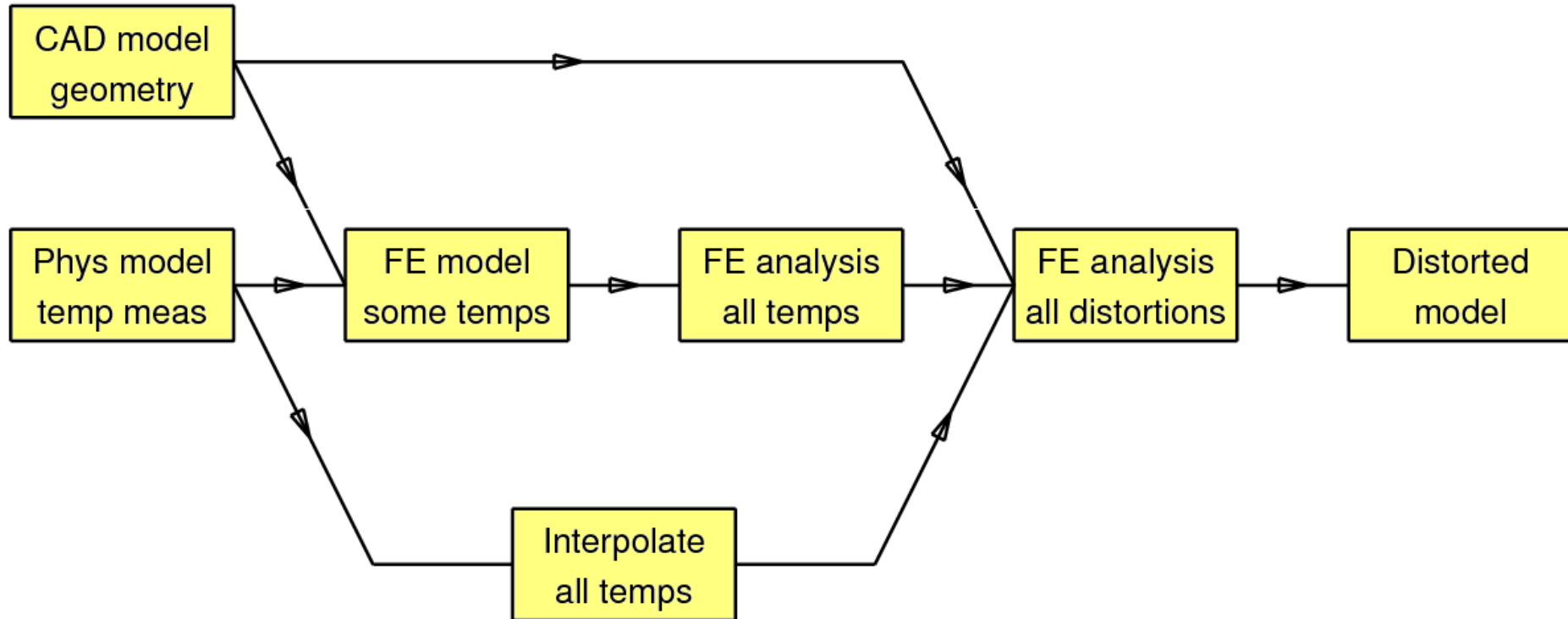
Can the thermal analysis stage in the FE process be avoided?





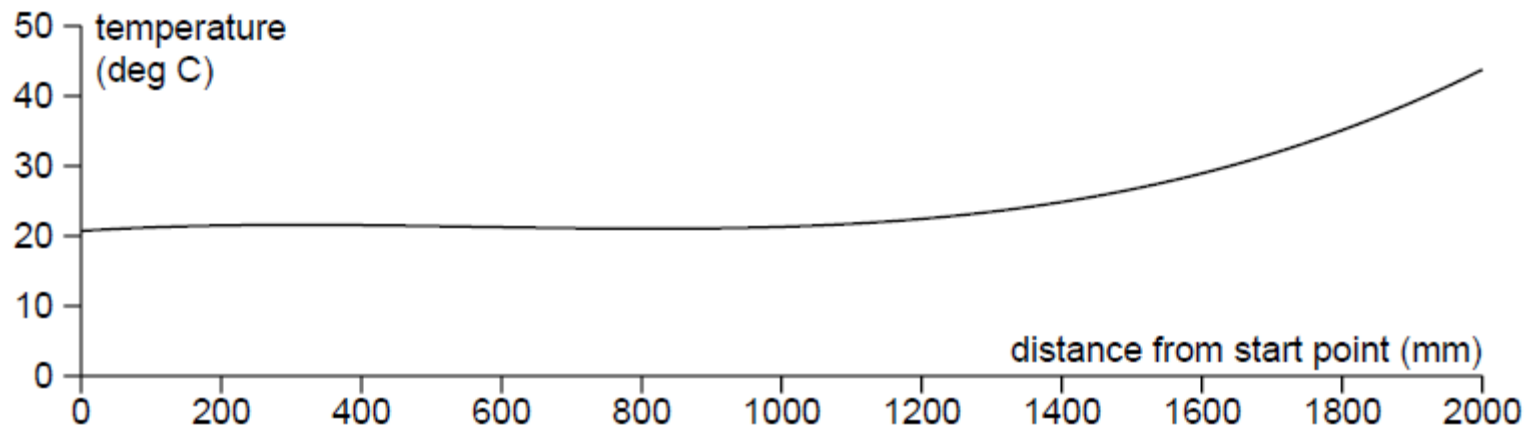


* boundary conditions
* time stepping

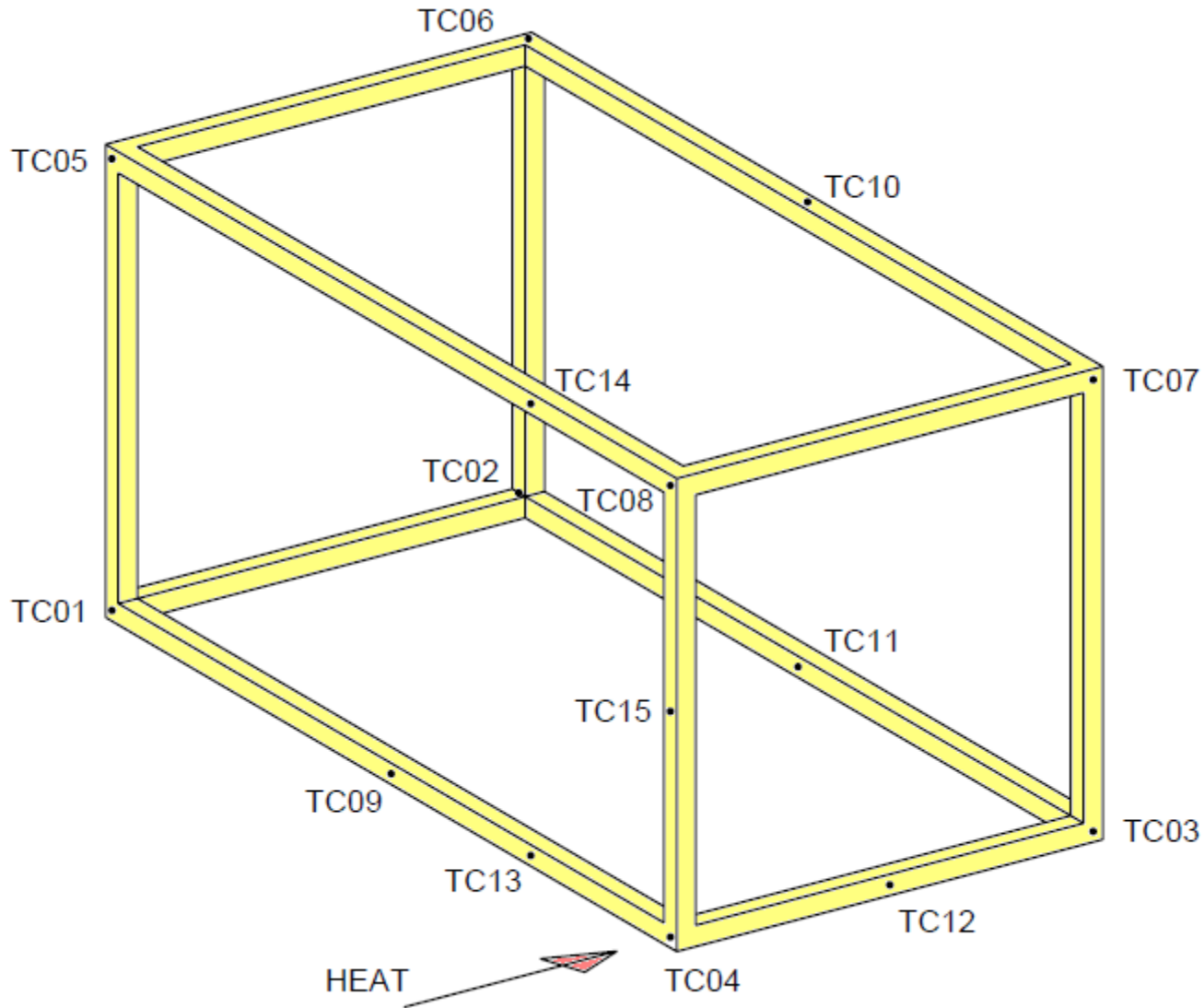


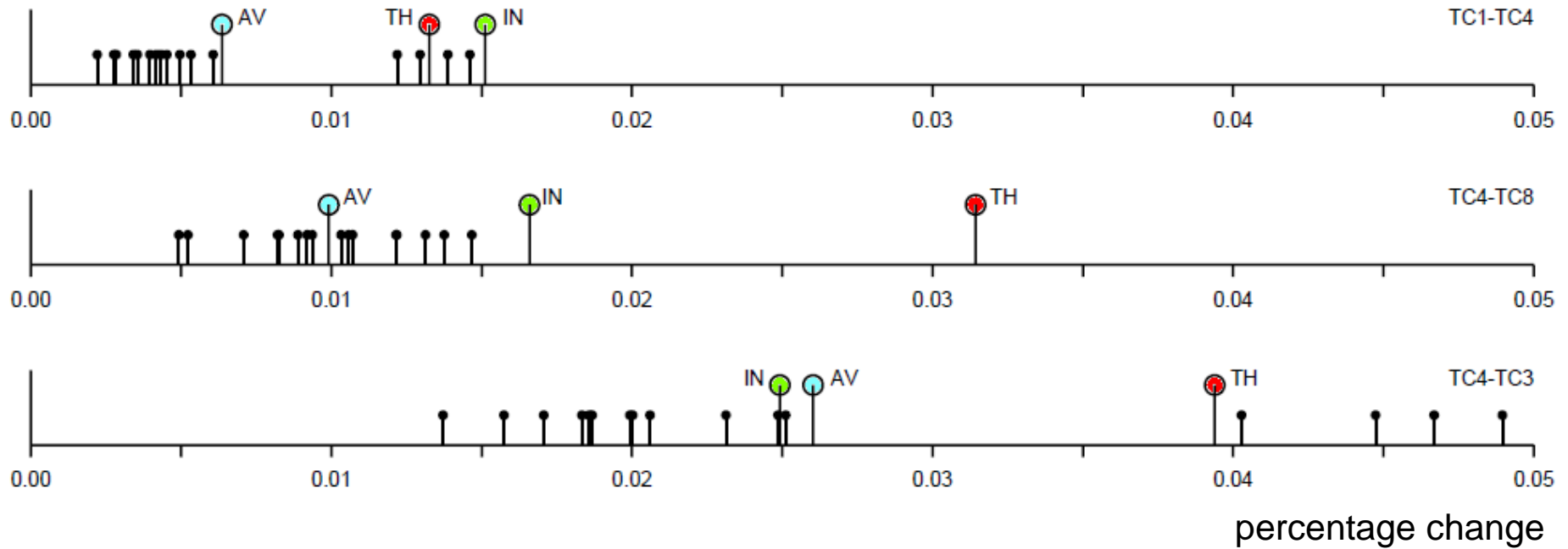
- regard temperature measurement points as forming “edges” in the body
- interpolate along each edge
- interpolate away from edges

point	x (mm)	y (mm)	z (mm)	θ ($^{\circ}\text{C}$)
tc01	39.0	56.4	1046.4	20.73
tc09	1039.0	56.4	1046.4	21.31
tc13	1516.55	56.4	1046.4	26.23
tc04	2039.0	56.4	1046.4	43.78



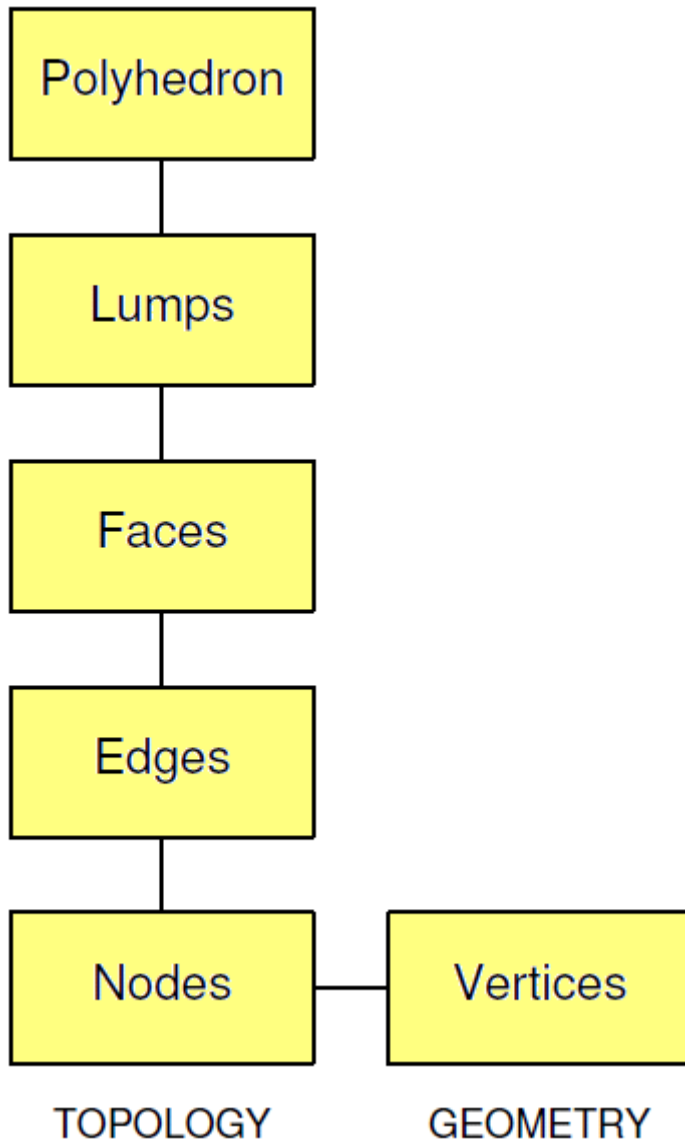
Frame example





Improving FE results on the basis of measurement results

- establish a rigid-body transform at each of the measured points
- interpolate these transforms over the whole body
- for any point, transform its FE result by the interpolated transform



- transform defined at each node
- interpolate across each item of the structure

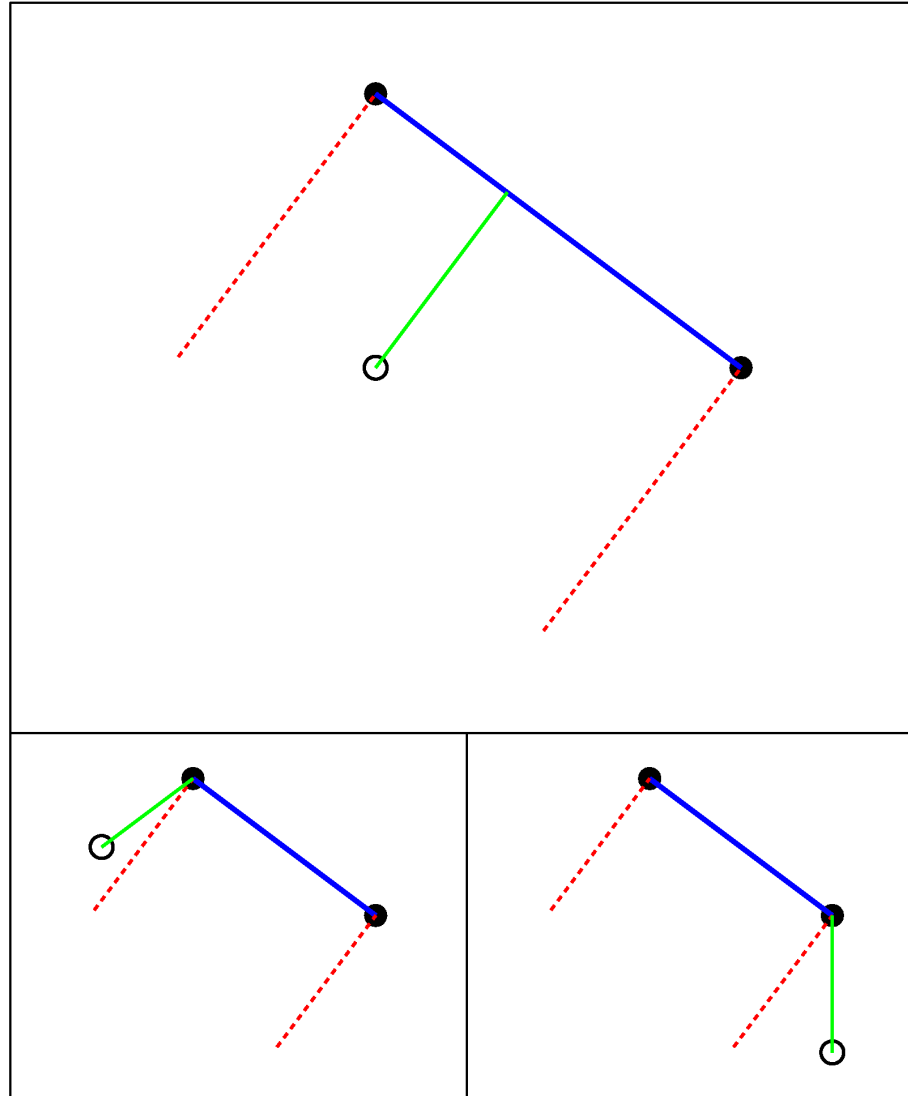
$$S(\mathbf{r}) = \sum_{V \text{ in } L} w_{\text{lump}}(V, \mathbf{r}, L) S(V)$$

Sum over
vertices

Weighting
function

Transform
at a vertex

Distance functions: point-to-edge example



Weights

$$w_{\text{node}}(V, \mathbf{r}, N) = \begin{cases} 1 & \text{if } V \in N \text{ and } \|\mathbf{r} - V\| = 0 \\ 0 & \text{if } V \in N \text{ and } \|\mathbf{r} - V\| \neq 0 \\ 0 & \text{if } V \notin N \end{cases}$$

$$w_{\text{edge}}(V, \mathbf{r}, E) = \begin{cases} \frac{\sum_{N \in E} w_{\text{node}}(V, N, \text{proj}(\mathbf{r}, N)) / \text{dist}(\mathbf{r}, N)}{\sum_{N \in E} 1 / \text{dist}(\mathbf{r}, N)} & \text{if } V \in E \\ 0 & \text{if } V \notin E \end{cases}$$

$$w_{\text{face}}(V, \mathbf{r}, F) = \begin{cases} \frac{\sum_{E \in F} w_{\text{edge}}(V, E, \text{proj}(\mathbf{r}, E)) / \text{dist}(\mathbf{r}, E)}{\sum_{E \in F} 1 / \text{dist}(\mathbf{r}, E)} & \text{if } V \in F \\ 0 & \text{if } V \notin F \end{cases}$$

$$w_{\text{lump}}(V, \mathbf{r}, L) = \begin{cases} \frac{\sum_{F \in L} w_{\text{face}}(V, F, \text{proj}(\mathbf{r}, F)) / \text{dist}(\mathbf{r}, F)}{\sum_{F \in L} 1 / \text{dist}(\mathbf{r}, F)} & \text{if } V \in L \\ 0 & \text{if } V \notin L \end{cases}$$

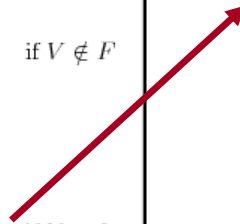
Weights

$$w_{\text{node}}(V, \mathbf{r}, N) = \begin{cases} 1 & \text{if } V \in N \text{ and } \|\mathbf{r} - V\| = 0 \\ 0 & \text{if } V \in N \text{ and } \|\mathbf{r} - V\| \neq 0 \\ 0 & \text{if } V \notin N \end{cases}$$

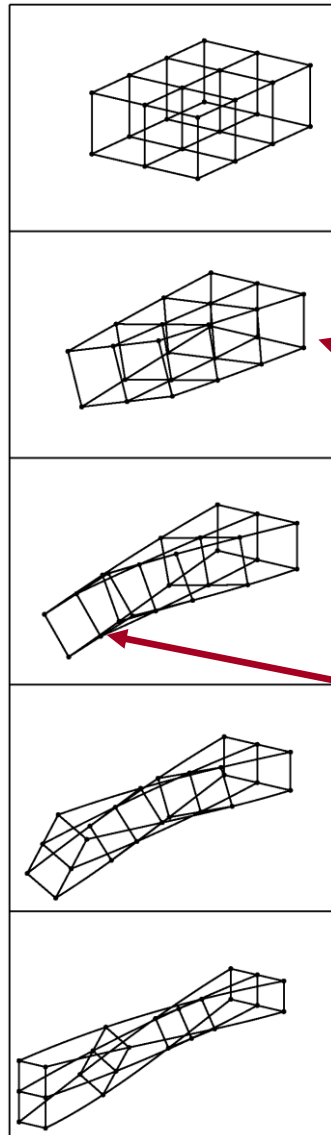
$$w_{\text{lump}}(V, \mathbf{r}, L) = \begin{cases} \frac{\sum_{F \in L} w_{\text{face}}(V, F, \text{proj}(\mathbf{r}, F)) / \text{dist}(\mathbf{r}, F)}{\sum_{F \in L} 1 / \text{dist}(\mathbf{r}, F)} & \text{if } V \in L \\ 0 & \text{if } V \notin L \end{cases}$$

$$w_{\text{face}}(V, \mathbf{r}, F) = \begin{cases} \frac{1}{\sum_{E \in F} 1 / \text{dist}(\mathbf{r}, E)} & \text{if } V \in F \\ 0 & \text{if } V \notin F \end{cases}$$

$$w_{\text{lump}}(V, \mathbf{r}, L) = \begin{cases} \frac{\sum_{F \in L} w_{\text{face}}(V, F, \text{proj}(\mathbf{r}, F)) / \text{dist}(\mathbf{r}, F)}{\sum_{F \in L} 1 / \text{dist}(\mathbf{r}, F)} & \text{if } V \in L \\ 0 & \text{if } V \notin L \end{cases}$$



Cuboid: twist and stretch

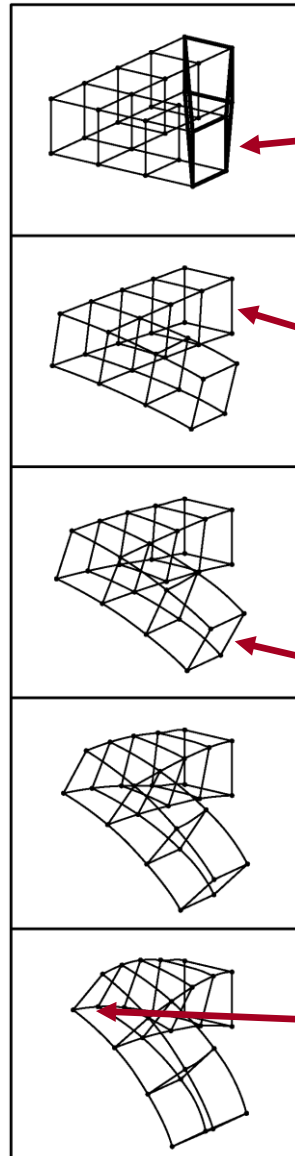


- cuboid is its own polyhedron

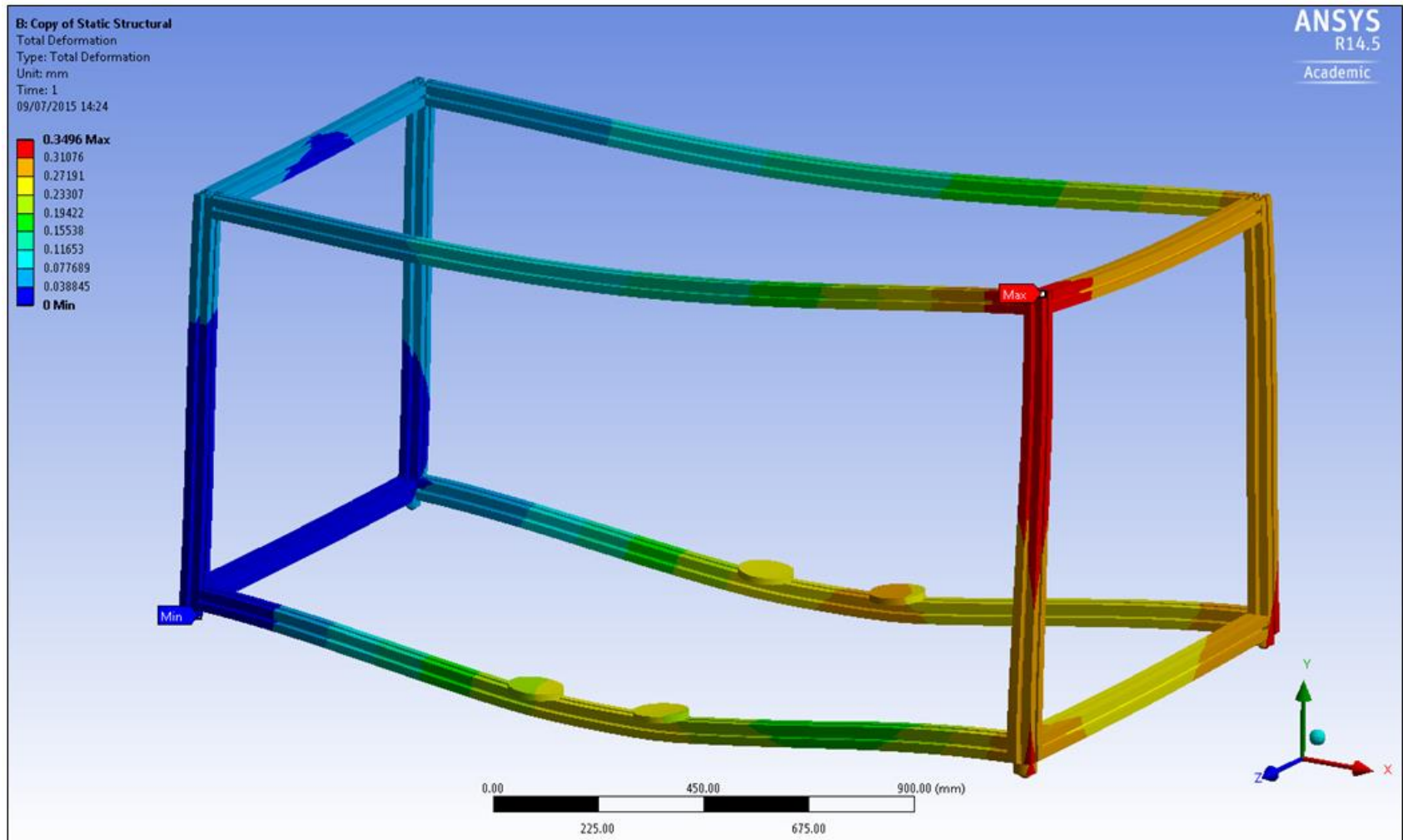
- back four nodes fixed

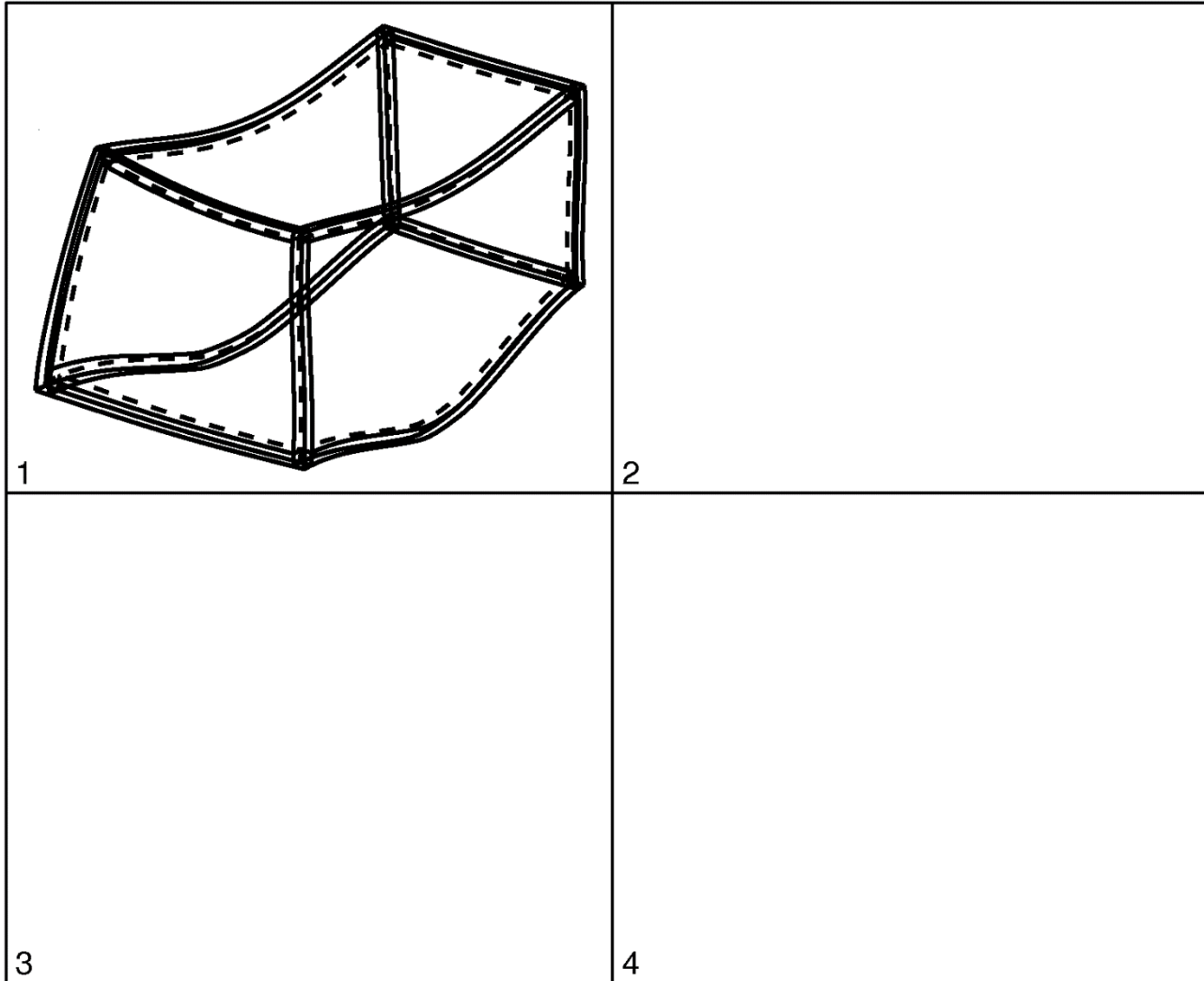
- front four nodes pulled forward and twisted

L-shaped block: twist

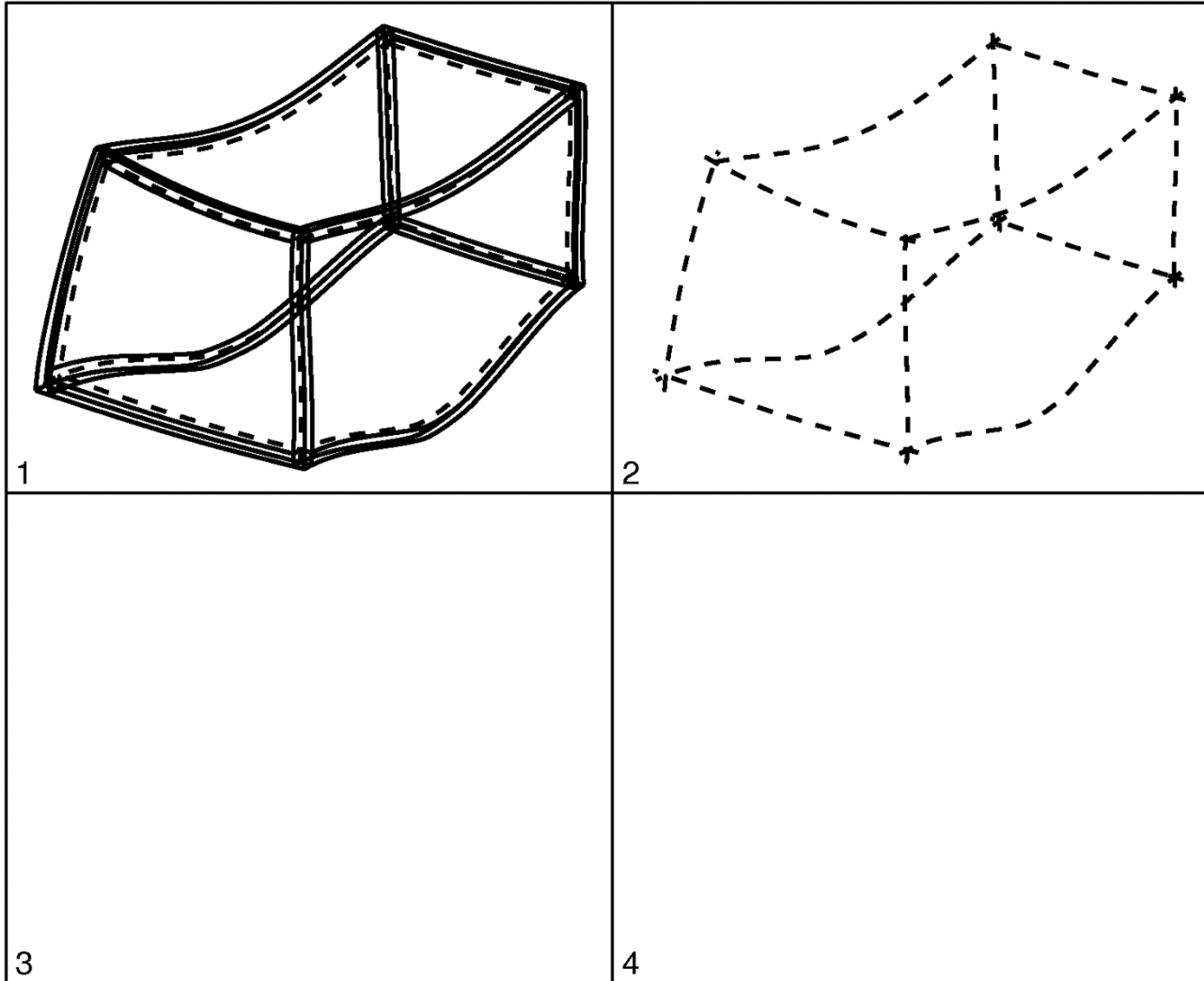


- polyhedron covers only part of block
- back four nodes fixed
- other four nodes twisted
- remaining nodes move smoothly



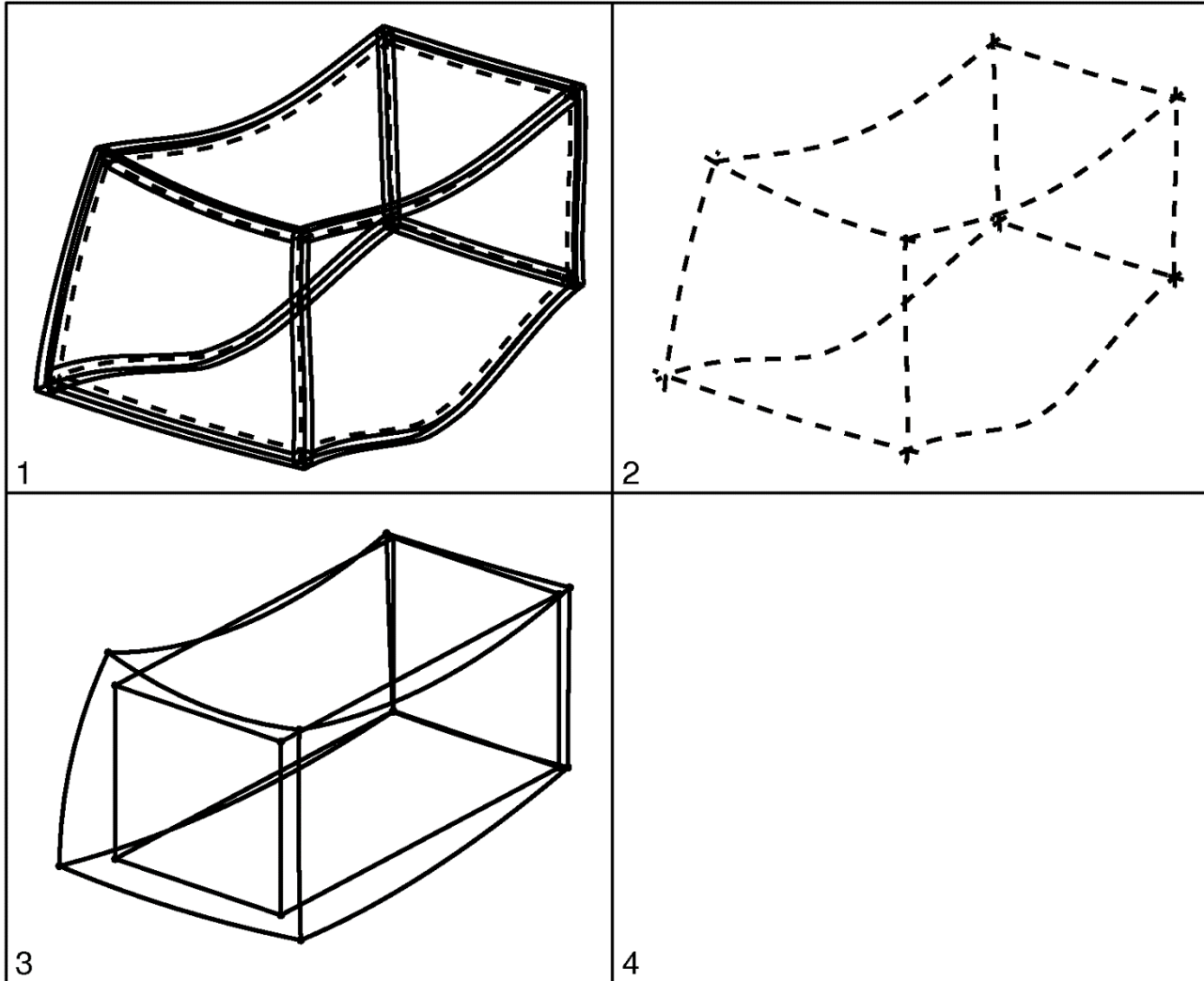


**FEA model of
deformation**



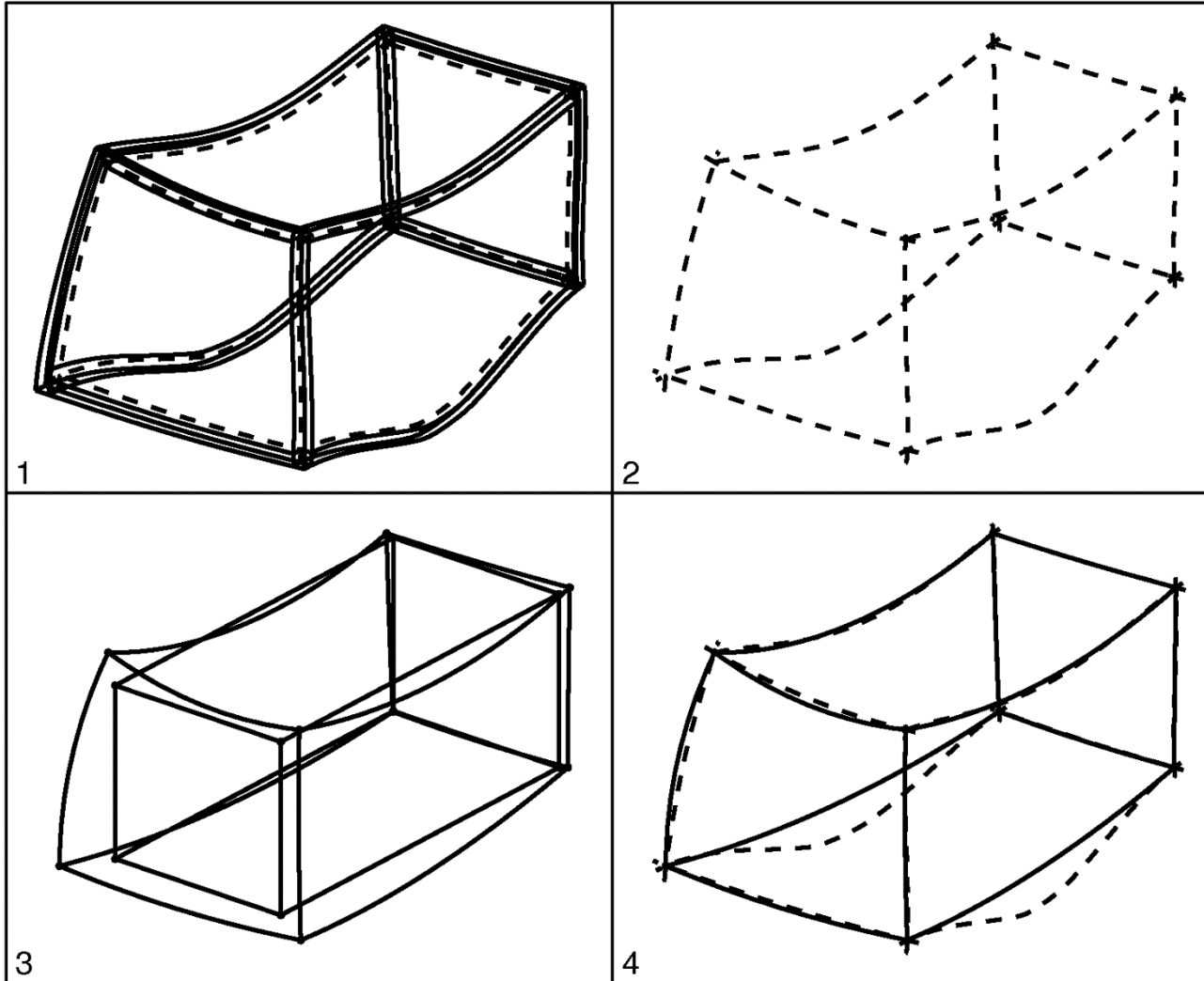
**Extract inner
cuboid**

Comparison example



**Compare with
original**

Comparison example



**Interpolate
transforms**

- problem of thermal/gravitational effects when measuring
- hybrid approach: geometric model and physical component
- FE to predict distortions
- can replace explicit thermal analysis with interpolation
- can adjust FE results so that they agree with measured results

