

Inspection techniques: Thermography

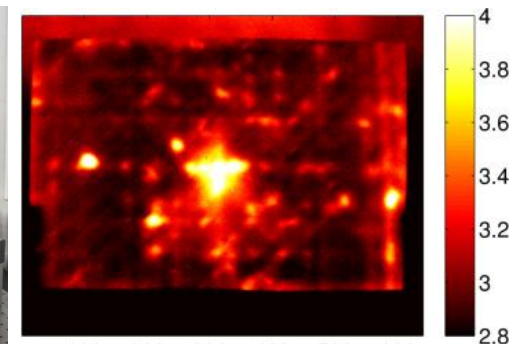
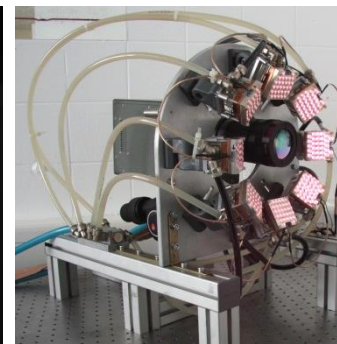
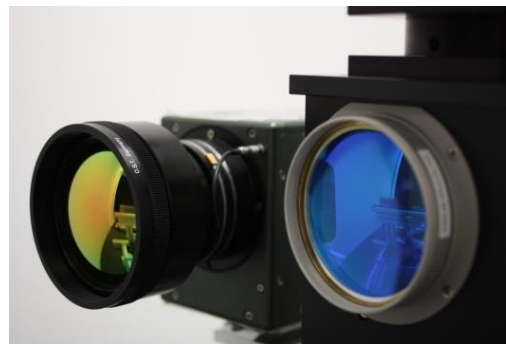
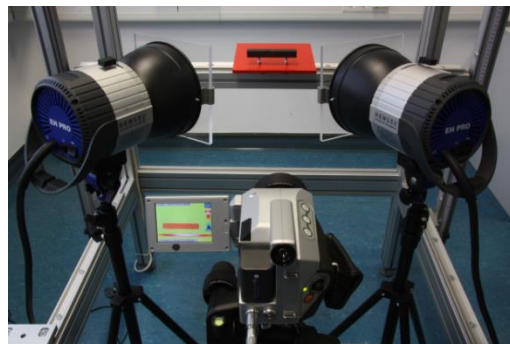
C. Maierhofer, R. Krankenhagen, S. Augustin

BAM Federal Institute for Materials Research and Testing

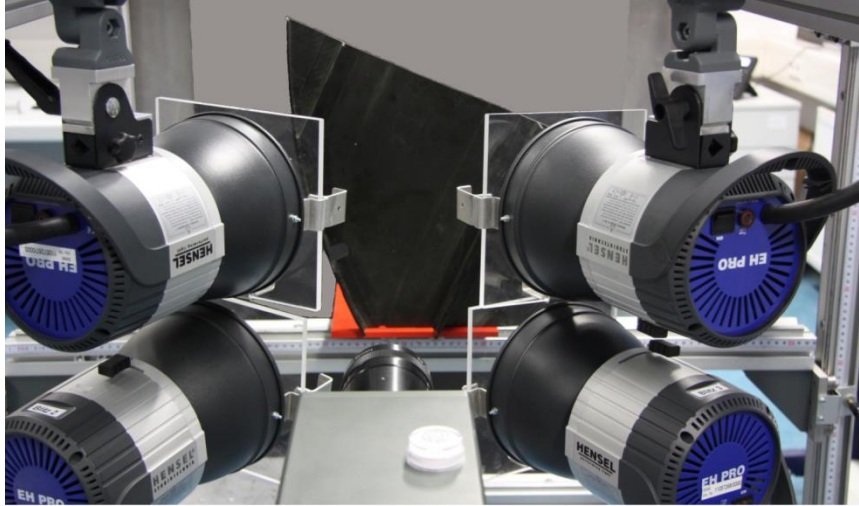
C. Monte, B. Gutschwager, A. Adibekyan, J. Hollandt

Physikalisch-Technische Bundesanstalt

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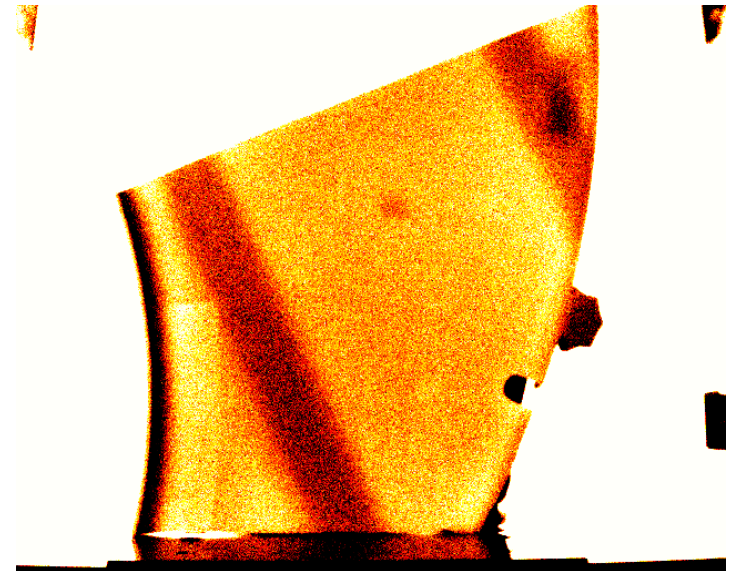
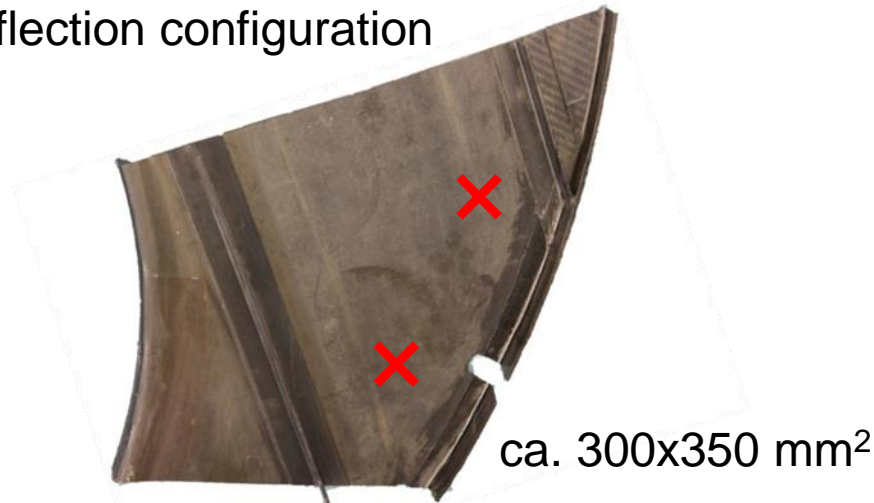
Flash thermography of an airplane side rudder



- Reflection configuration using 4 flashes from the front side
- InSb IR camera, 640x512 pixel
- 100 Hz frame rate
- Subtraction of zero image
- Measurement duration: 10 s

*C. Maierhofer et al, Composites Part B
57, 2014, 35-46*

Reflection configuration



- Development of theoretical models for **analytical and numerical simulation** of heat transfer in anisotropic or partially translucent materials
- Investigations of **artificial defect artefacts**
- Investigation of **natural defect artefacts**
- **Round robin tests** and **field trials**
- **POD study**
- Comparison to the **other NDT methods**

- Characterisation of **flat panel reference source** for infrared camera temperature calibration
- Determination of **anisotropic thermal properties** of CFRP materials
- Determination of **optical properties of partial translucent GFRP material**



Heat equation

Non-stationary heat conduction process in anisotropic solids is described by the proportionality of heat flux and temperature gradient using the **heat equation** (diffusion equation):

$$\rho(\vec{r}) c_p(\vec{r}) \frac{\partial T(\vec{r}, t)}{\partial t} = \nabla \cdot [\lambda(\vec{r}) \nabla T(\vec{r}, t)] + q(\vec{r})$$

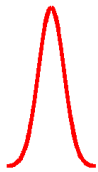
T : temperature	λ : therm. conductivity	q : introduced heat
r : position vector	ρ : density	per volume
t : time	c : spec. heat capacity	∇ : nabla operator

Solution of parabolic DE:

- Spatial boundary conditions (temperature or heat flux) have to be set
- Temporal starting conditions, i.e. temperature distribution at $t = 0$, have to be set
- Strong attenuation

Comparison to solution of hyperbolic DE (wave equation):

- Spatial boundary conditions have to be set
- Two temporal starting conditions: temperature distribution at $t=0$ and first derivative to time
- Little attenuation



Solution for Dirac pulse (flash excitation)

$$T(z, t) = \frac{q}{\varepsilon \sqrt{\pi t}} e^{-z^2/4\alpha t}, \quad T(0, t) = \frac{q}{\varepsilon \sqrt{\pi t}}$$

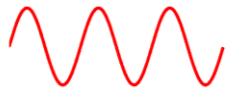
1D, for semi-infinite isotropic bodies

$$\varepsilon = \sqrt{\lambda \rho c} \quad \text{Effusivität}$$

$$\alpha = \frac{\lambda}{\rho c} \quad \text{Diffusivität}$$

$$L_{\max} = \frac{q}{\rho c} \frac{1}{n \cdot \Delta T_{NETD}}$$

Max. penetration depth L_{\max} depends on heat density, NETD of IR camera **and on density and spec. heat capacity** (n=2 to 3)



Solution for periodic heating (lockin excitation)

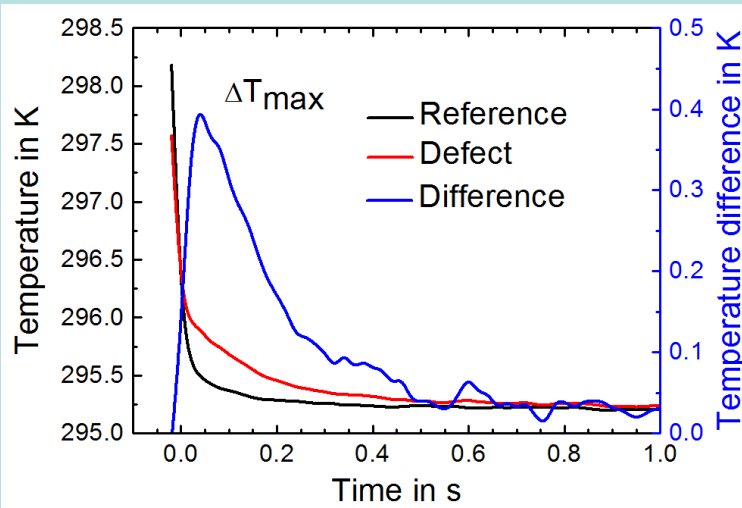
$$T(z, t) = T_0 e^{-z/\mu} \cdot e^{-i(\omega t - z/\mu - \pi/4)}$$

$$\mu = \sqrt{\frac{2\alpha}{\omega}}$$

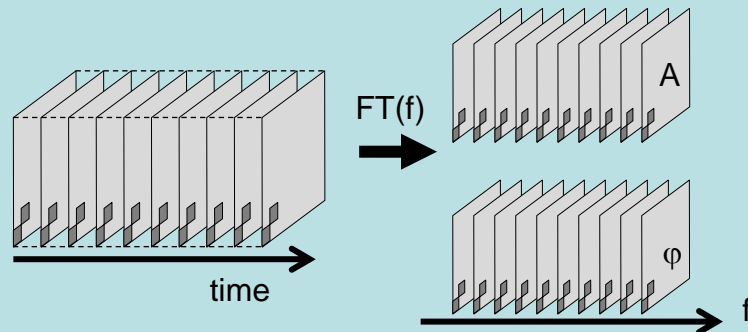
Penetration depth of thermal wave:

- decreases with increasing frequency
- increases with increasing diffusivity α

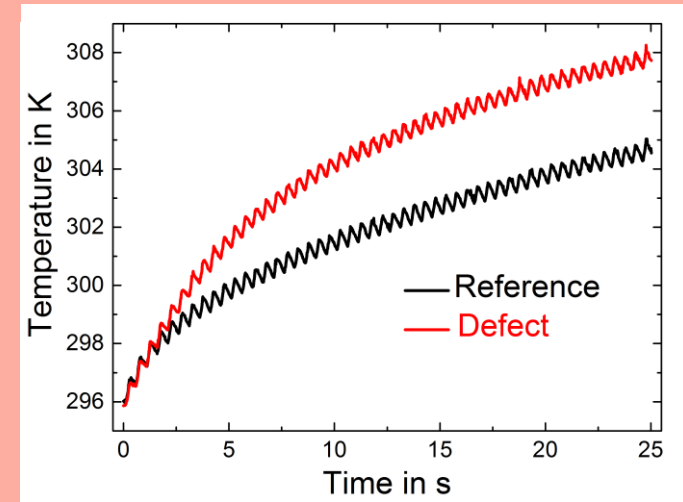
Flash thermography



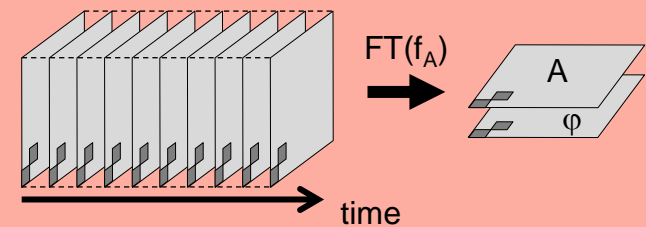
- Thermograms at raising or max. contrast
- **Pulse-Phase-Thermography (PPT)**
- Thermal signal reconstruction (TSR)

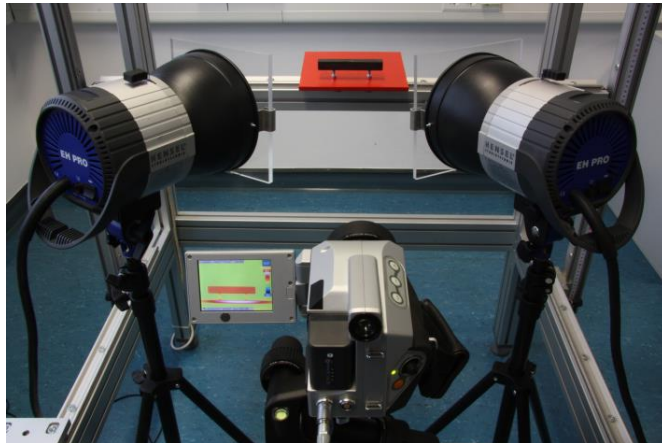


Lockin thermography



- Online **FFT** or 4 point method at excitation frequency
- Offline **FFT** at excitation frequency





Flash excitation

4 flash lamps with
6 kJ each

>> 24 kJ

Duration of impulse:
2.6 ms

Duration of measurement:
1 to 3 min

Infrared camera

InSb detector 640x512

2 to 5 μm

NETD of 25 mK

Full frame rate: 300 Hz



Lockin excitation

2 halogen lamps with
1.25 kW each **>> 2.5 kW**

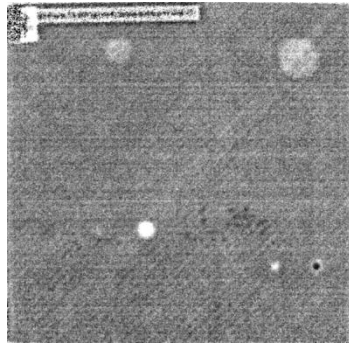
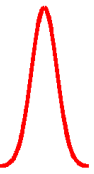
Frequencies: 0.01 to 1 Hz

Periods: 10 to 180

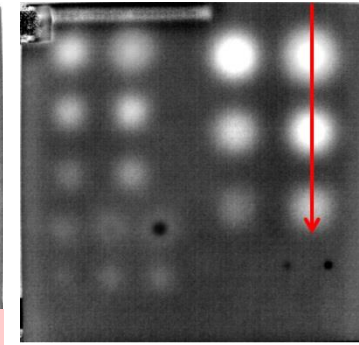
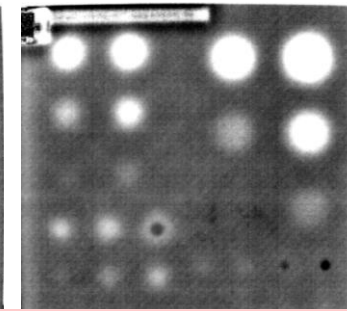
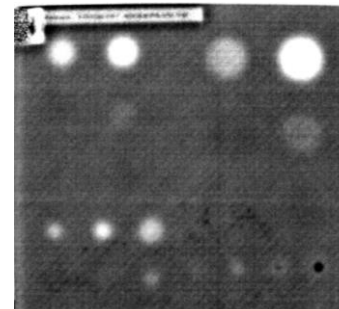
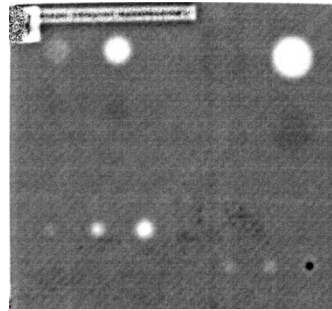
>> 250 to 1500 kJ

Duration of measurement:
3 to 15 min

Phase images of artificial FBH

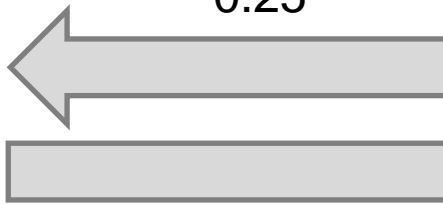


0.25

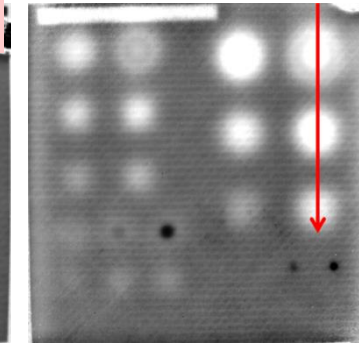
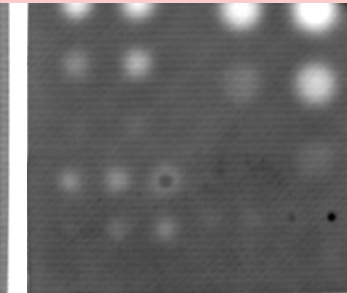
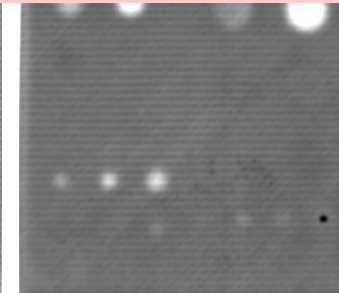
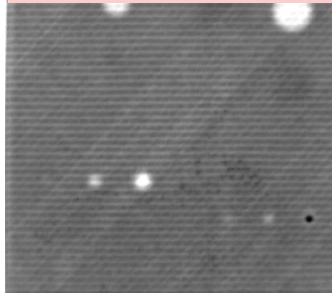
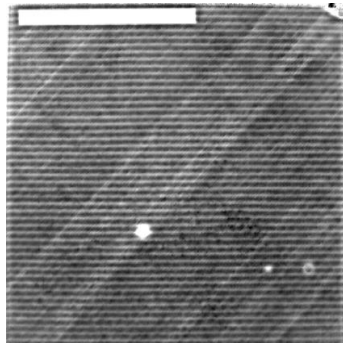


0.01

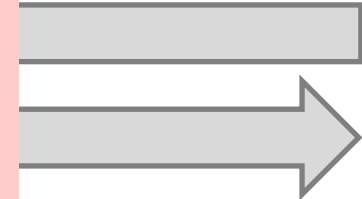
- Phase images of both excitation methods look very similar, phase wrap is similar
- For flash excitations, the holes appear slightly earlier (at higher frequencies)
- All holes with larger diameter could be detected. For the 4 mm holes, only three to four holes are visible.

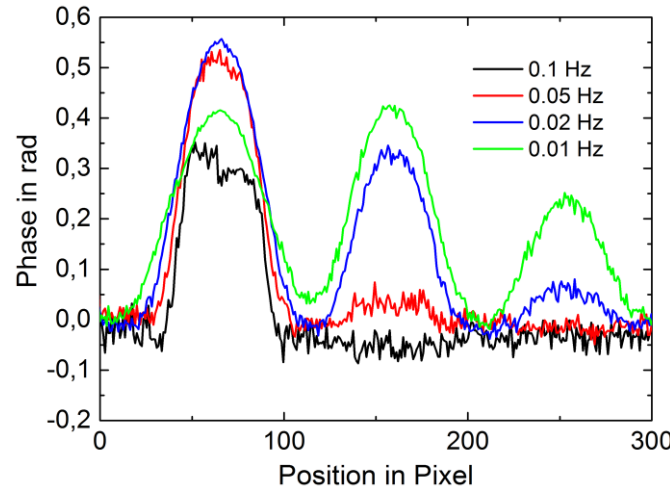
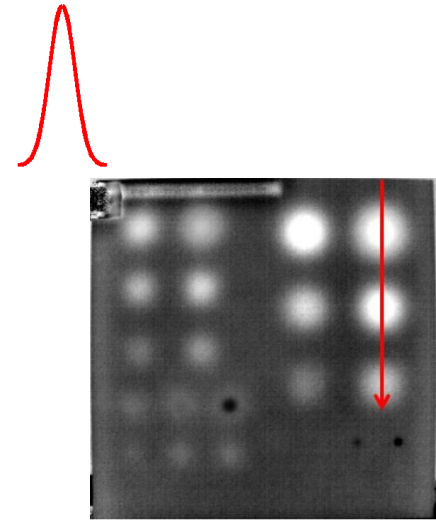


0.9



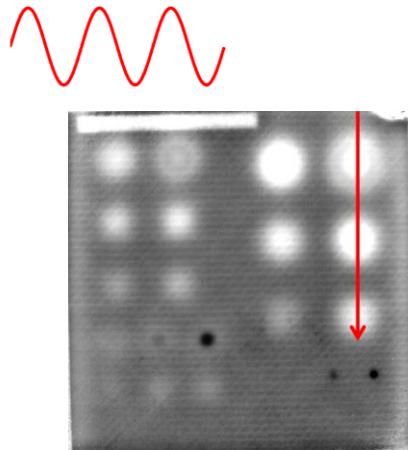
4.4



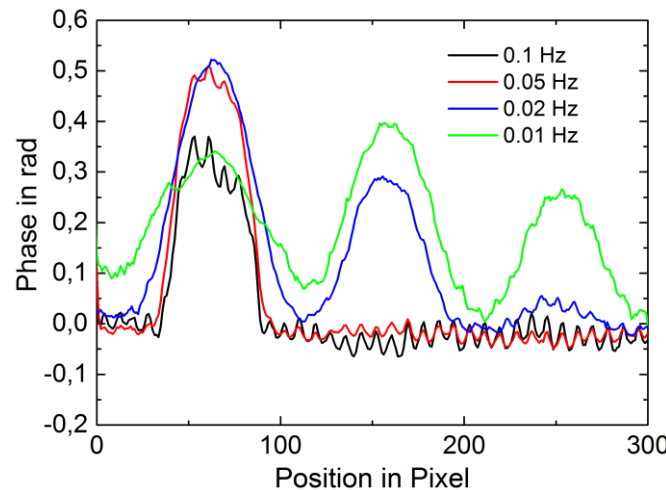


Comparison of spatial resolution of the phase images

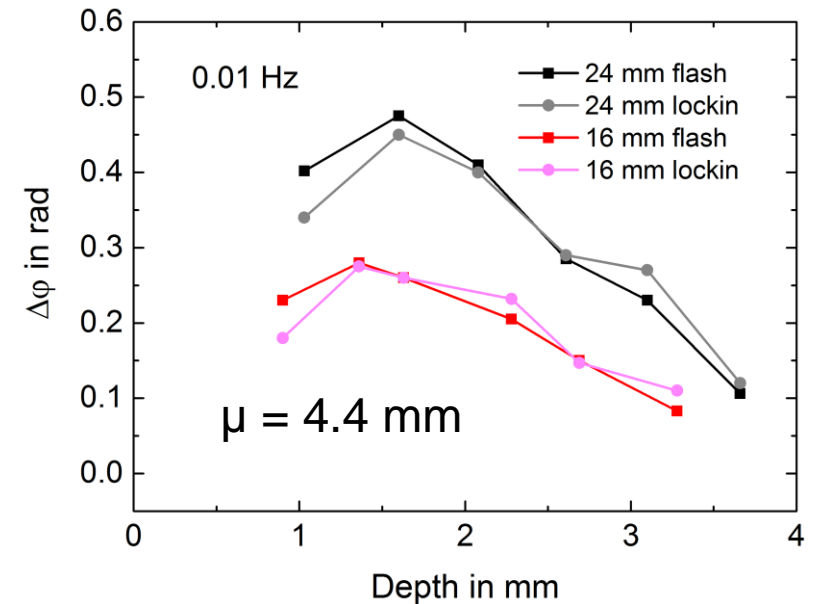
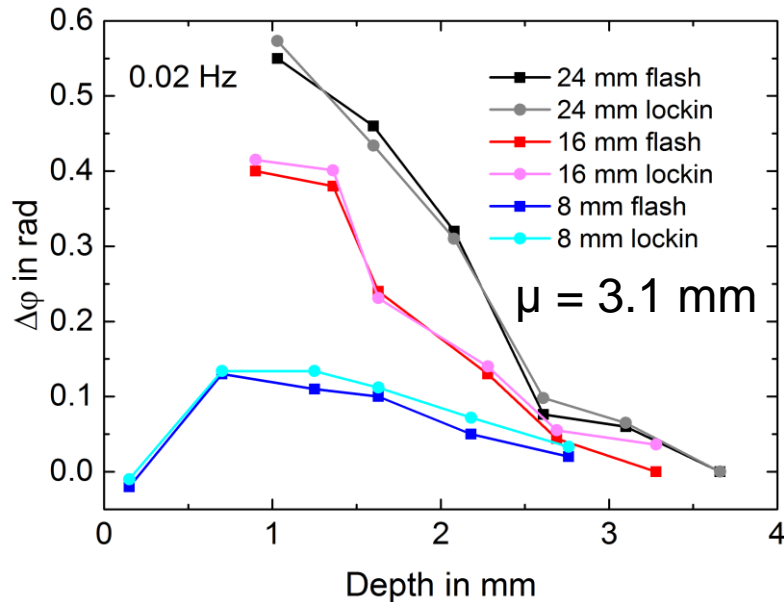
- along a line scan of 24 mm holes with wall thicknesses of 1, 2 and 3 mm
- **phase contrasts** of both methods are similar and are changing with frequency
- **SNR** is higher for lockin data
- **spatial resolution** of holes is better for flash data but ...
- ...in the lockin data, the **fibre bundles** could be resolved.



0.01 Hz



Influence of defect size, depth and excitation frequency on phase contrast



- Phase contrast is similar for flash and lockin excitation
- Phase contrast is higher for larger defects
- Optimum phase contrast depends on depth and frequency

- Maximum penetration depth depends on frequency:

$$\mu = \sqrt{\frac{\alpha}{\pi f}}$$

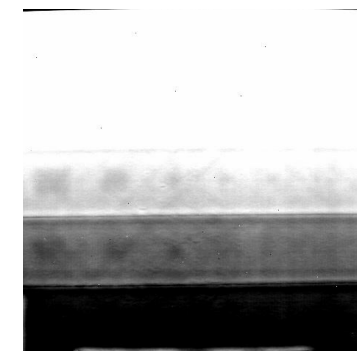
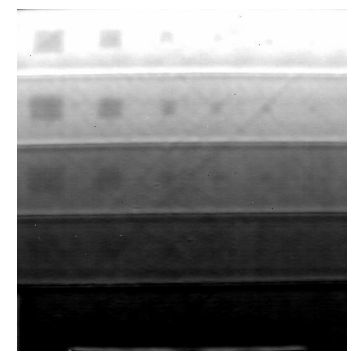
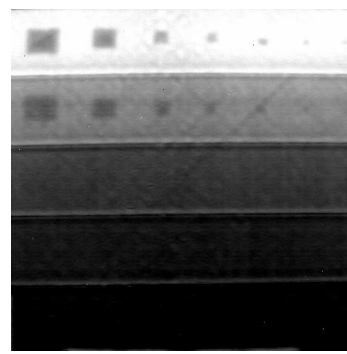
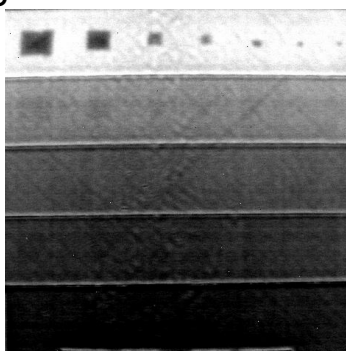
μ : penetration depth
 α : thermal diffusivity
 f : frequency

Phase images of delaminations



coverage in mm

0.5
1.0
1.5
2.0
2.5



1 Hz
0.45 mm

0.5 Hz

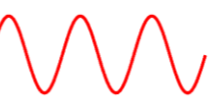
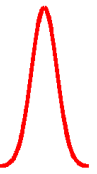
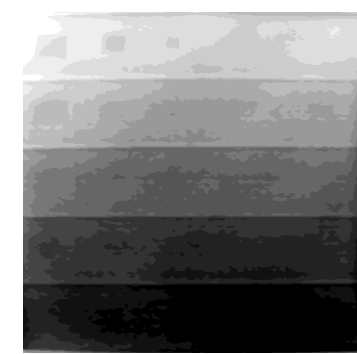
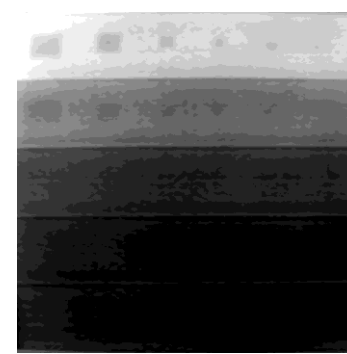
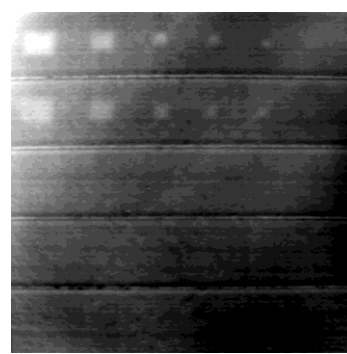
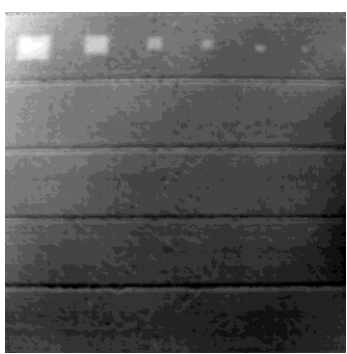
0.2 Hz

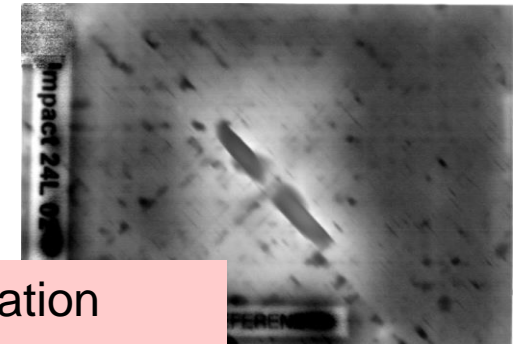
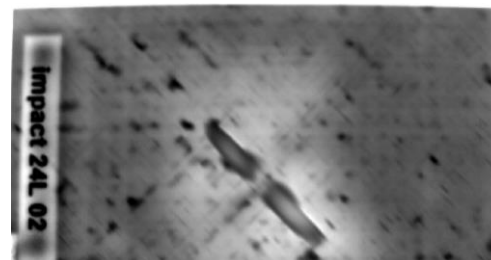
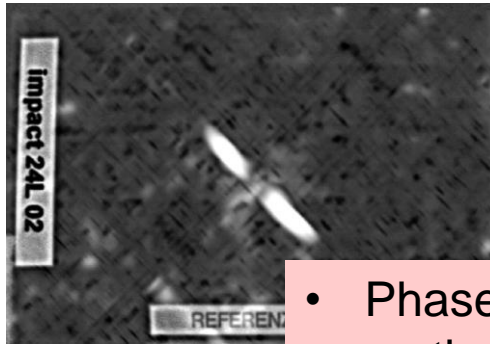
0.2 Hz
1 mm

- Phase images of both excitation methods look very different
- For flash excitations, larger defects up to a depth of 1.7 mm could be detected
- For lockin excitation, only the defects up to a depth of 0.9 mm could be detected

1 Hz, 190 periods
0.45 mm

5 Hz, 25 periods
2 mm

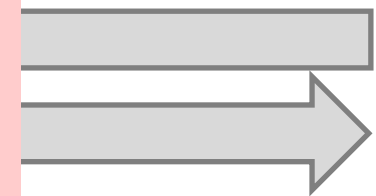
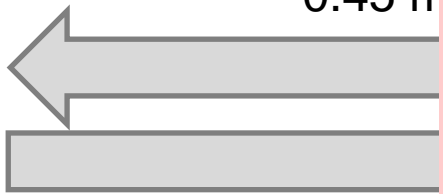
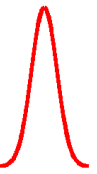
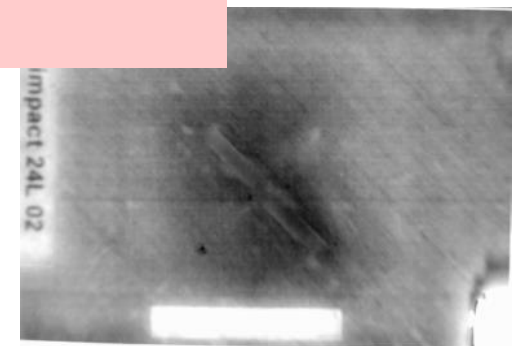
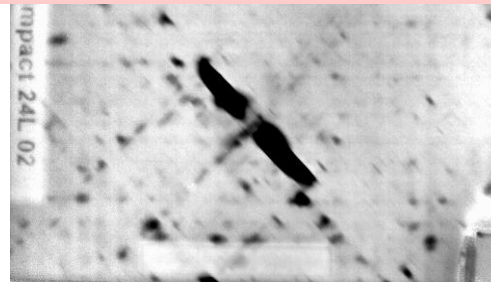
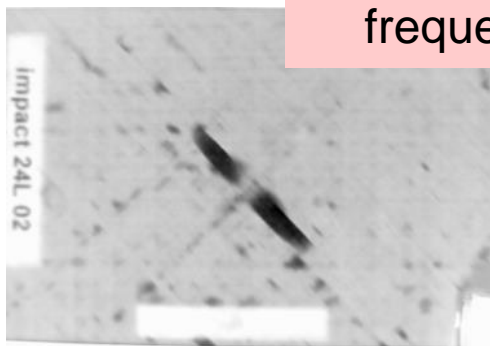




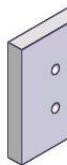
- Phase images at 1 Hz of both excitation methods look similar
- Phase images at lower frequencies are different, which might be related to a higher depth selectivity of lockin excitation (the structures close to the surface are not visible in the lockin phase images at lower frequencies)

1 Hz
0.45 mm

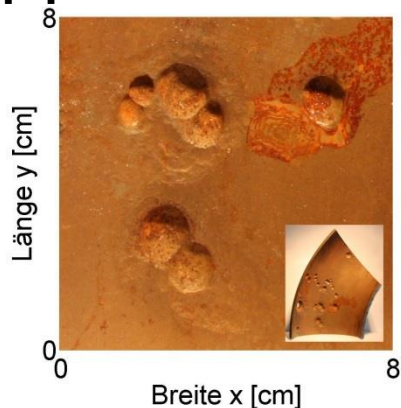
0.05 Hz
2 mm



back side
geometry
z

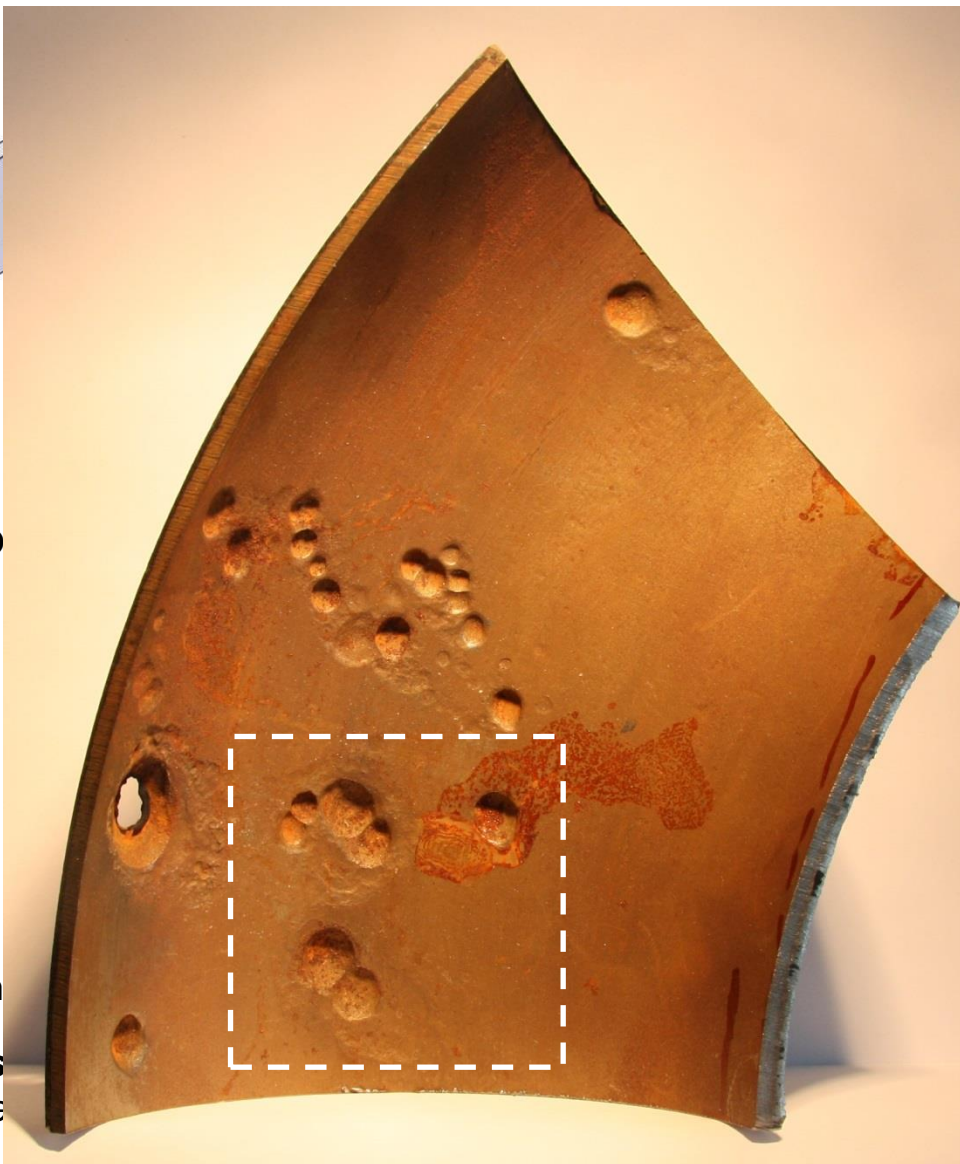


pipe with corrosion



Wall thickness: 3.6 mm

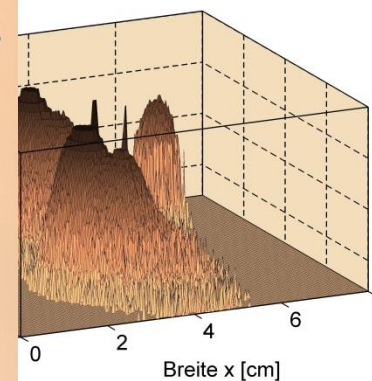
*Regina Richter, Diss.
TU Braunschweig, De*



front side
temperature field
 $T(x, y, t)$

Dimensions:
Parameters are known

Reconstruction



Reconstruction of
with ZIB

- **Detectability of defects as a function of defect size and defect depth (remaining wall thickness)**
- **Quantitative phase contrast of defects as a function of depth (remaining wall thickness)**
- **Signal-to-noise ratio (SNR) of defects**
- **Penetration depth**
- **Depth resolution**
- **Spatial resolution**

Next steps:

- Determination of thermal and optical material properties
- Systematic testing of new artificial reference defect artefacts (RDAs) with flash and periodic excitation
- Systematic analytical und numerical modelling of RDAs
- Numerical reconstruction